Online Space-time Travel Planning in Dynamic Graphs



Dynamic Graphs



























Space-Time Travel



Travel Delay



Travel Delay



Travel Cost







114













Related Work

SSS 2023

Necessary condition on the cost function

Offline ODOC problem is in P, even with a constraint on the cost, even in graphs evolving for infinity.

But, may create paradoxes!

Learning paradoxe



Learning paradoxe

Learning paradoxe

Competitive Ratio

Competitive Ratio

A is \hbar -competitive if

Competitive Ratio

A is \hbar -competitive if

$$\forall G, \quad \frac{Cost(A, G)}{Cost(Opt, G)} \leq \checkmark$$

middle

The following algorithm is 2-competitive for any f with $\lim_{x\to\infty} f(x) = \infty$

Algorithm 1 T-Online Algorithm

Input:

G': the known evolving graph

time: the current time

u: the current node (here u is always the starting node s)

Let T_{\max} be an optimal space-time travel in G', if it exists, starting at time 0, from node s to node d.

if T_{\max} does not exist or $\mathfrak{f}(time + 1) < cost(T_{\max})$ then | wait 1 time instant;

else

go back at time 0, then follow the travel T_{max} ;

This is optimal

Let G_i be

823

⁹ Space-Online Algorithm Lower Bound

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9

No!

 $\frac{2n}{3}$ is our best current LB

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Algo S-online

Algo S-online Each step cost ≤ optimal

Hlgo S-online # Each step cost ≤ optimal
★ AF most n-1 steps

Hlgo S-online Each step cost ≤ optimal * Ar moot n-1 steps

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Conclusion

- Optimal Time-Online algorithm
- Upper and lower bound for the Space-Online problem

- The punchline comes before the question
- What's the problem with Time Travel jokes ?

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Thank you!

