

Beedroids: How Luminous Autonomous Swarms of UAVs Can Save the World?

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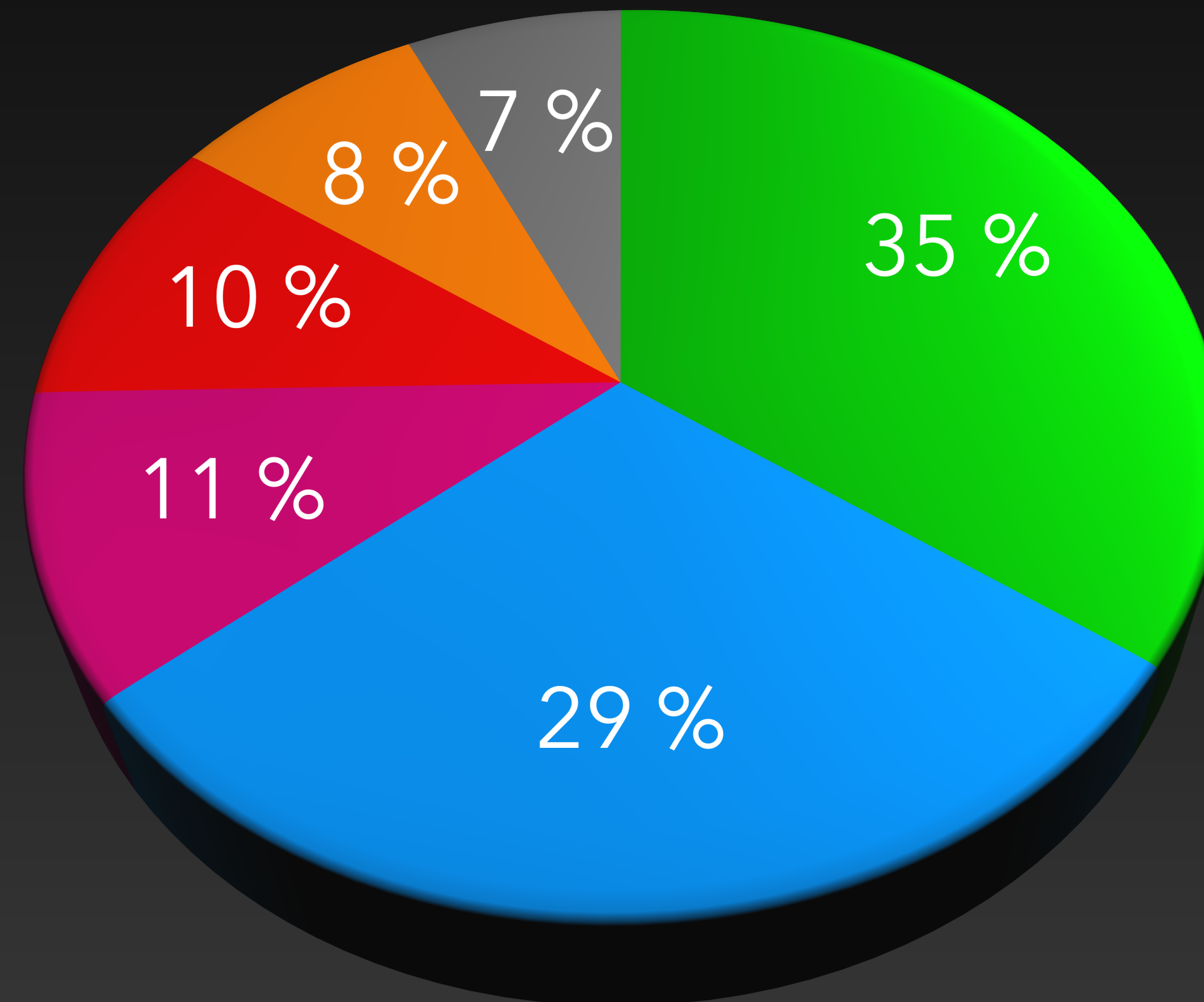
The world is endanger

Bees are dying!! (and other insects but that are less pretty so we don't care)

Our team received lots of
money to save the world.

How did we manage the
budget to save the world ?

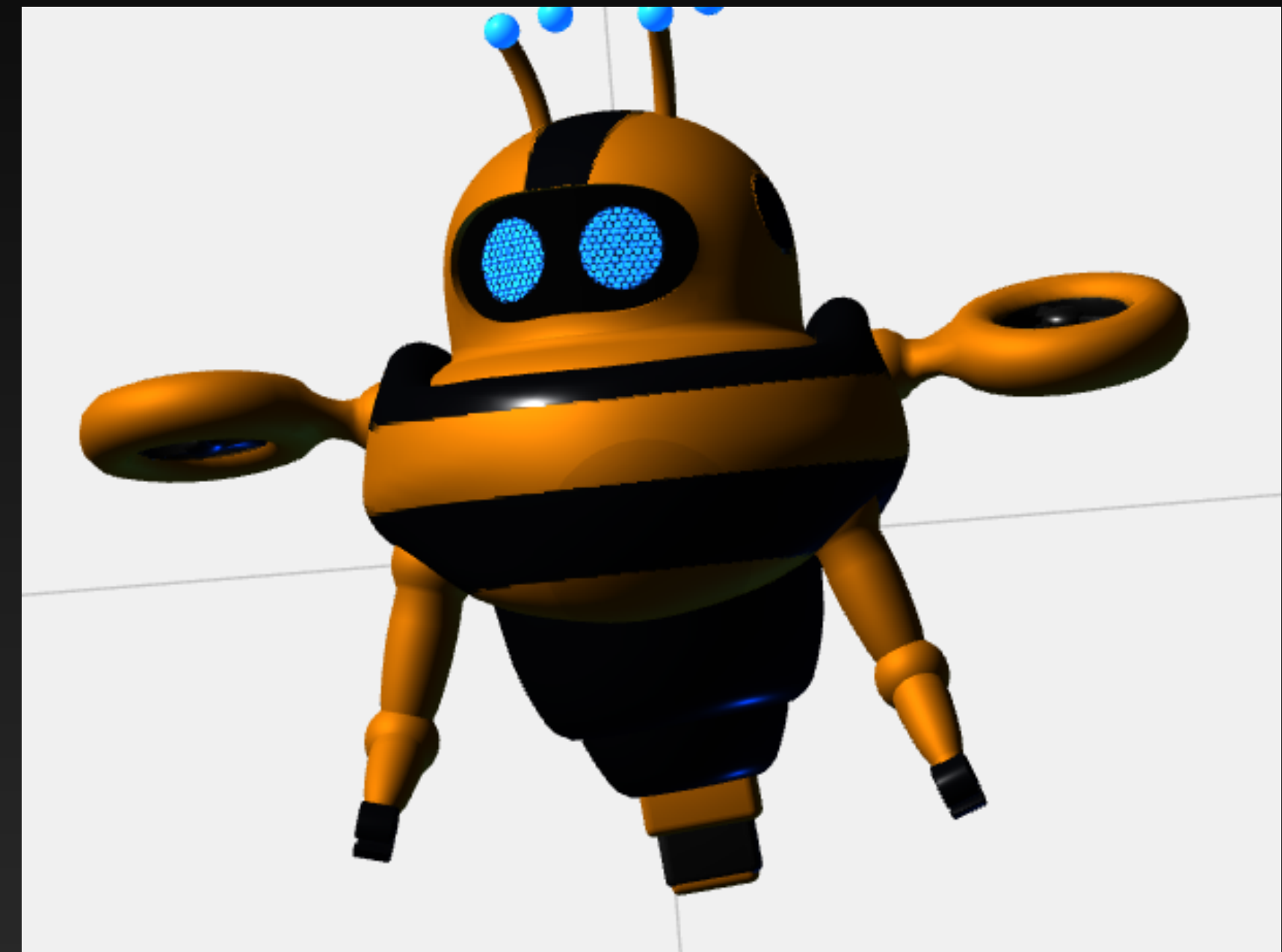
- Add green
- FUN Travel expense
- Coffee
- Very pretty 3D simulations
- Hiring a team of designers for this awesome presentation
- Thinking about a solution



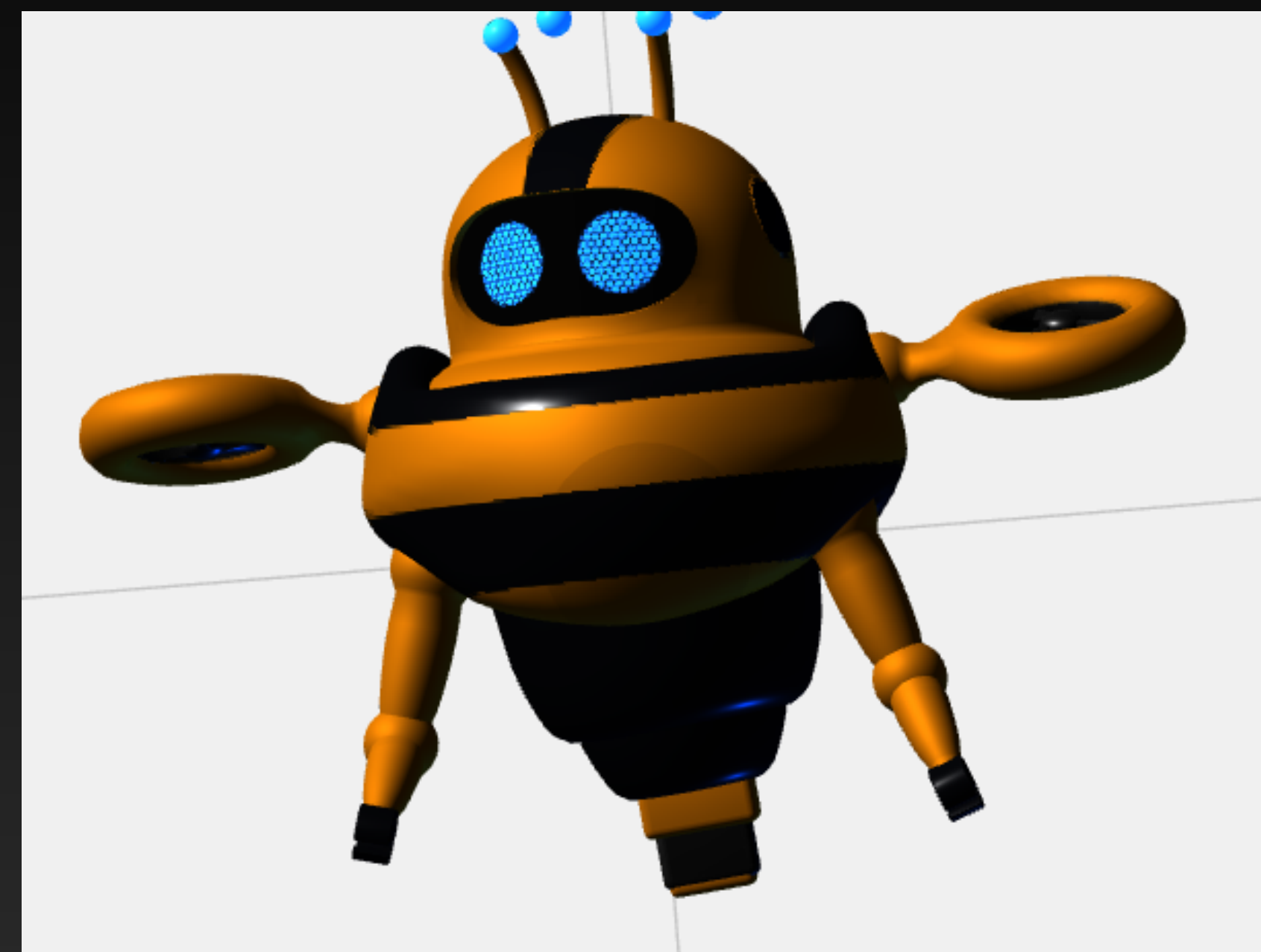
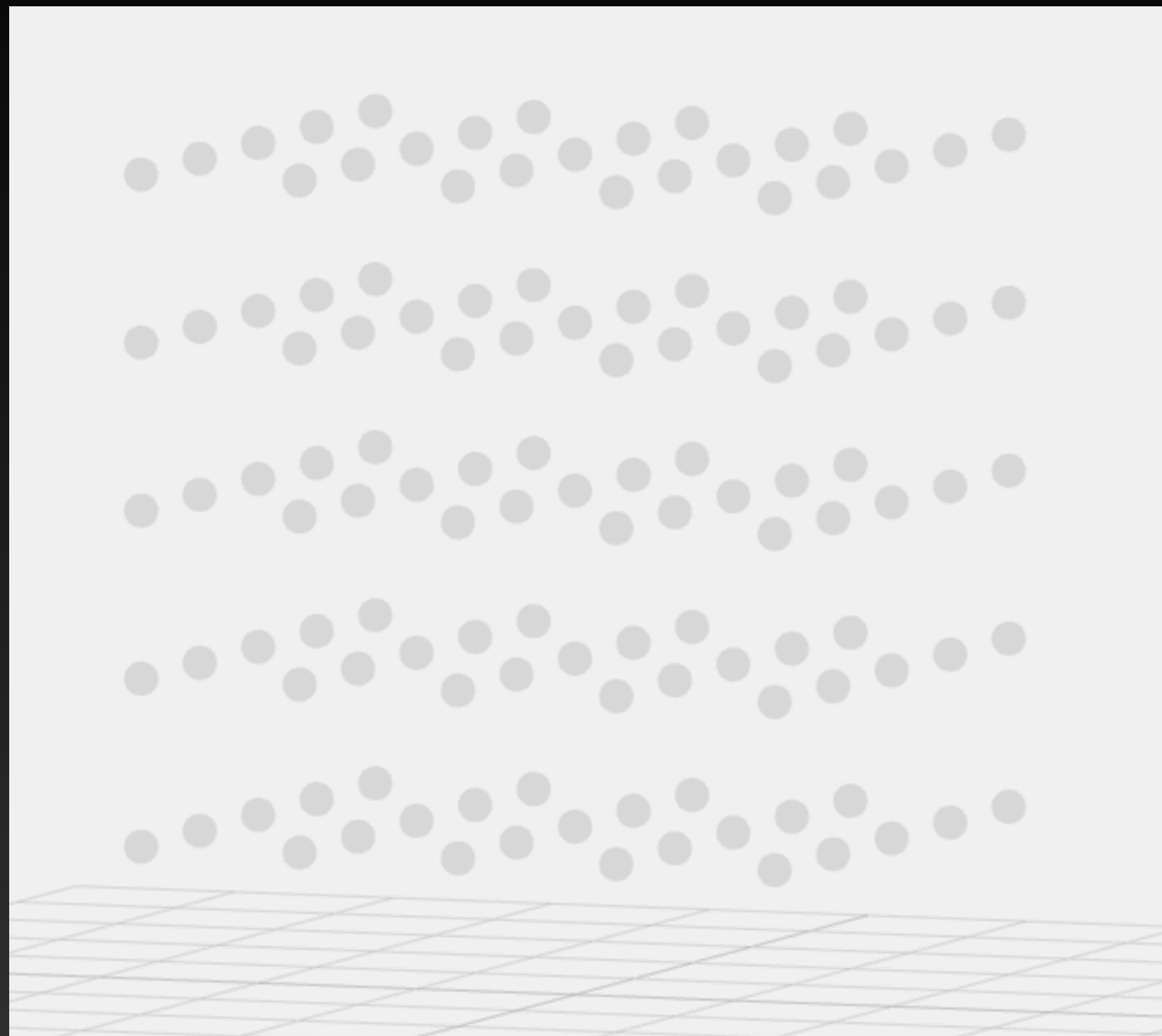
Myopic
Oblivious
Autonomous
Luminous
Flying Pollinating Robots

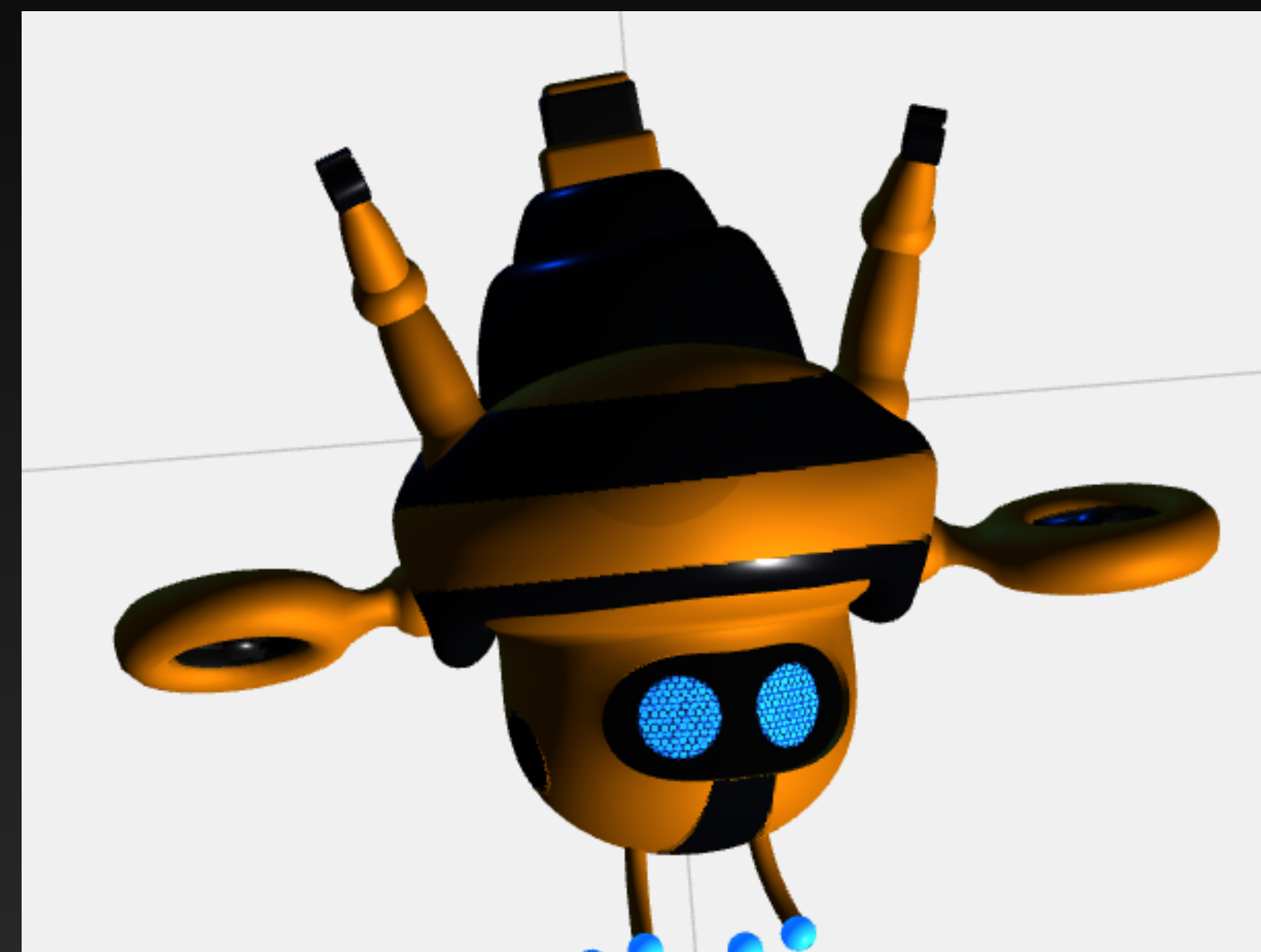
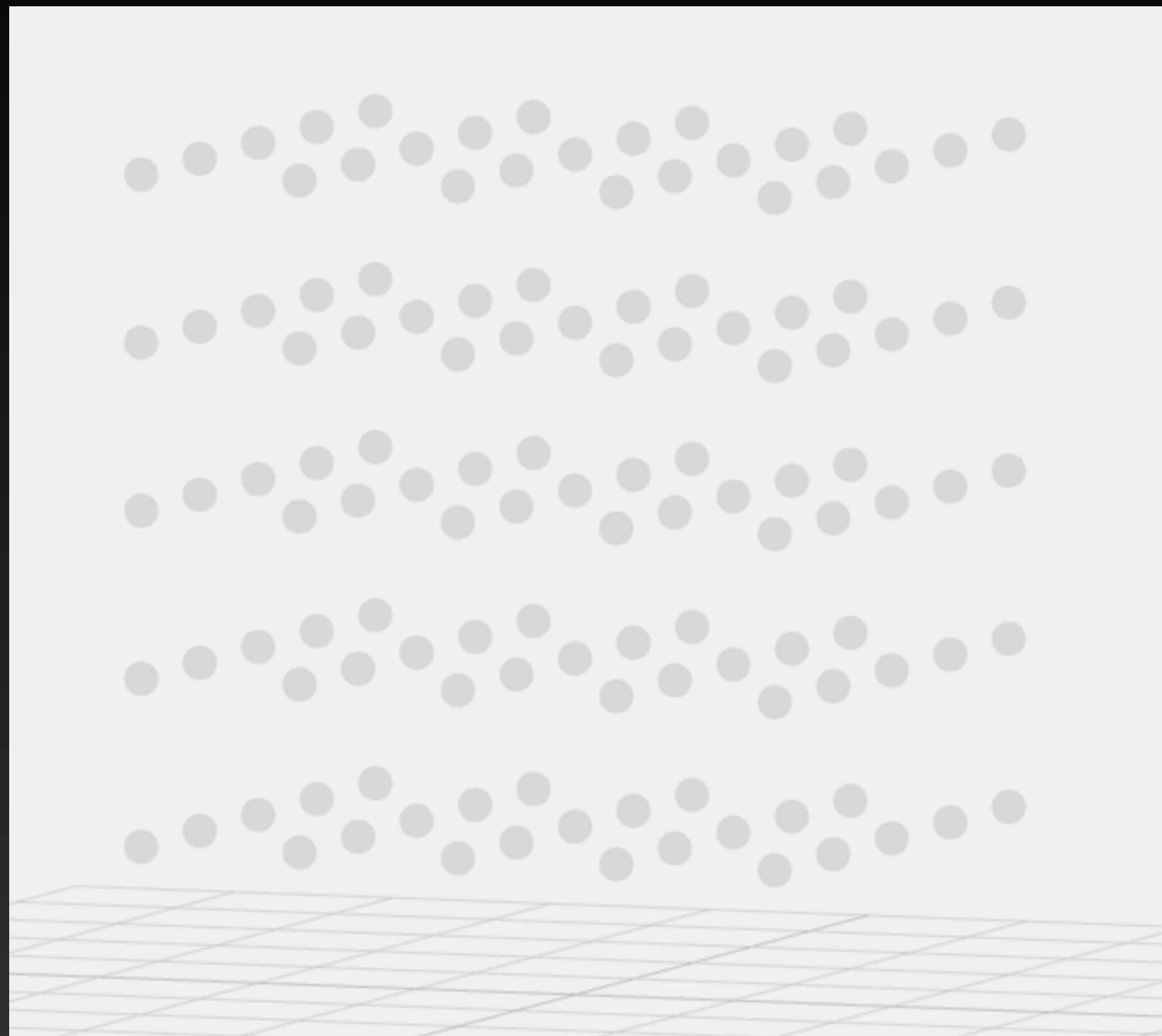


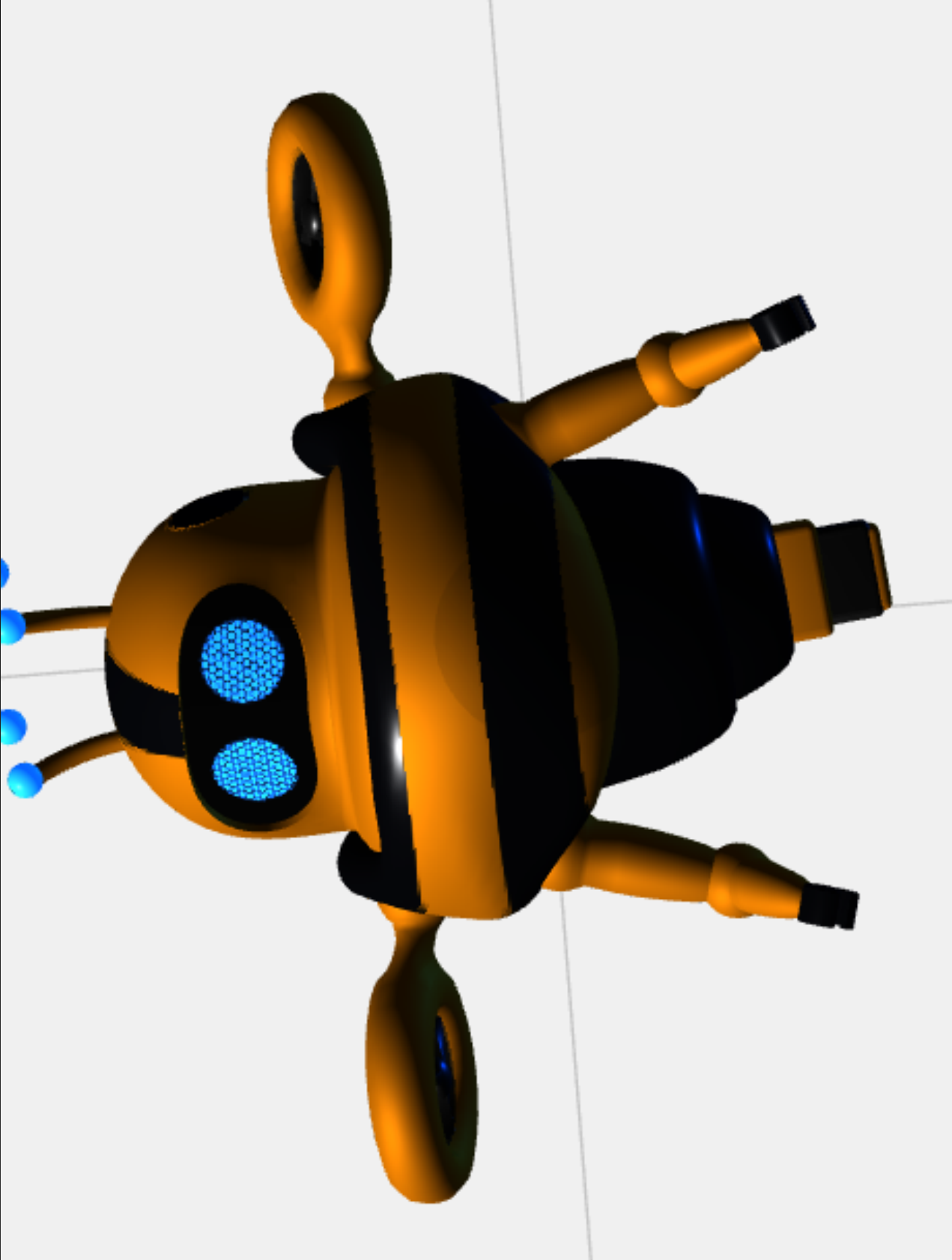
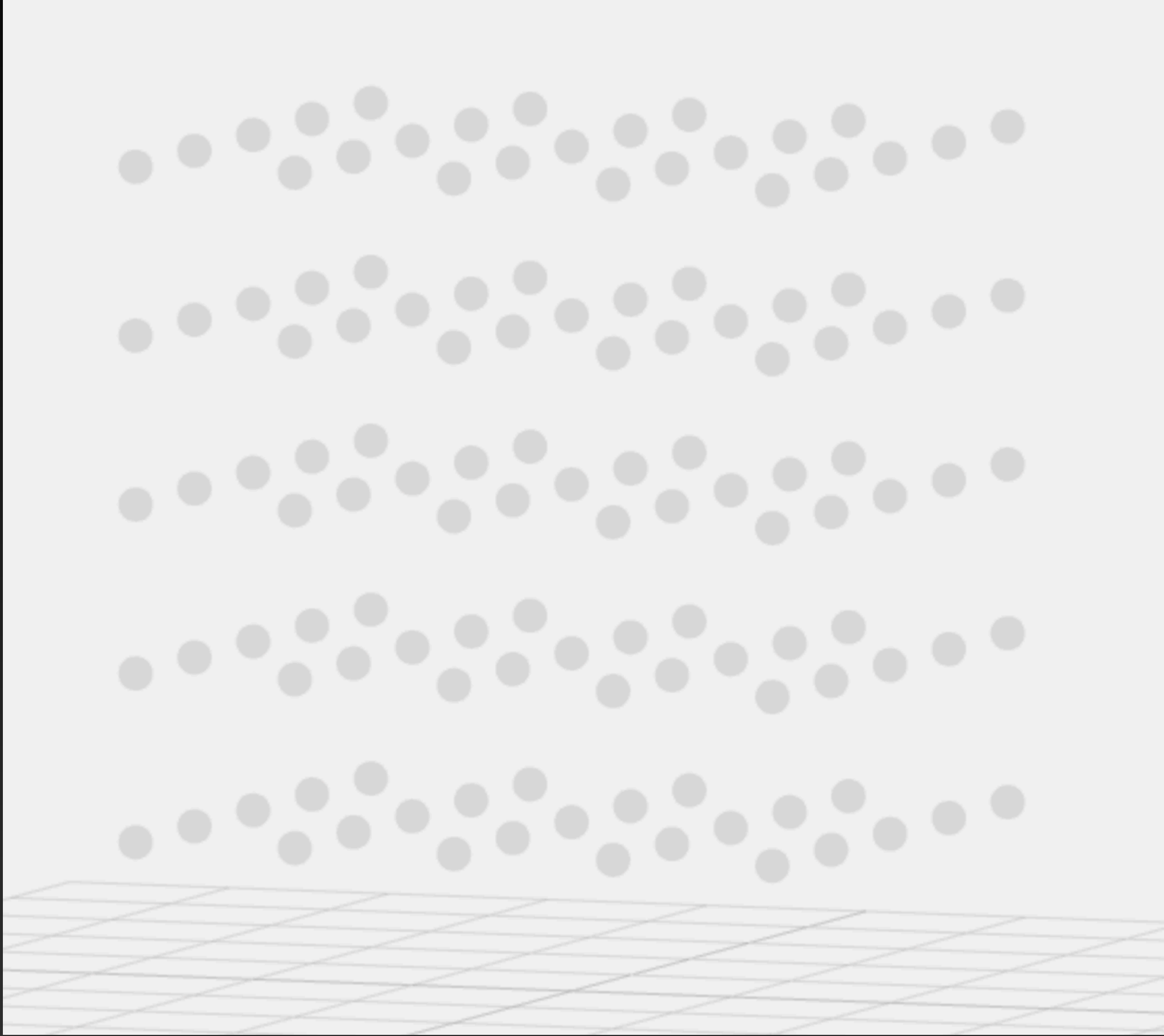
Myopic
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Author: <https://sketchfab.com/tehe4ek>







Removing unnecessary Hypothesis

« Hot Shots! » methodology

- Landing gear's frozen
- I lost my radar
- I'm out of fuel
- Lost a wing
- Lost the other one

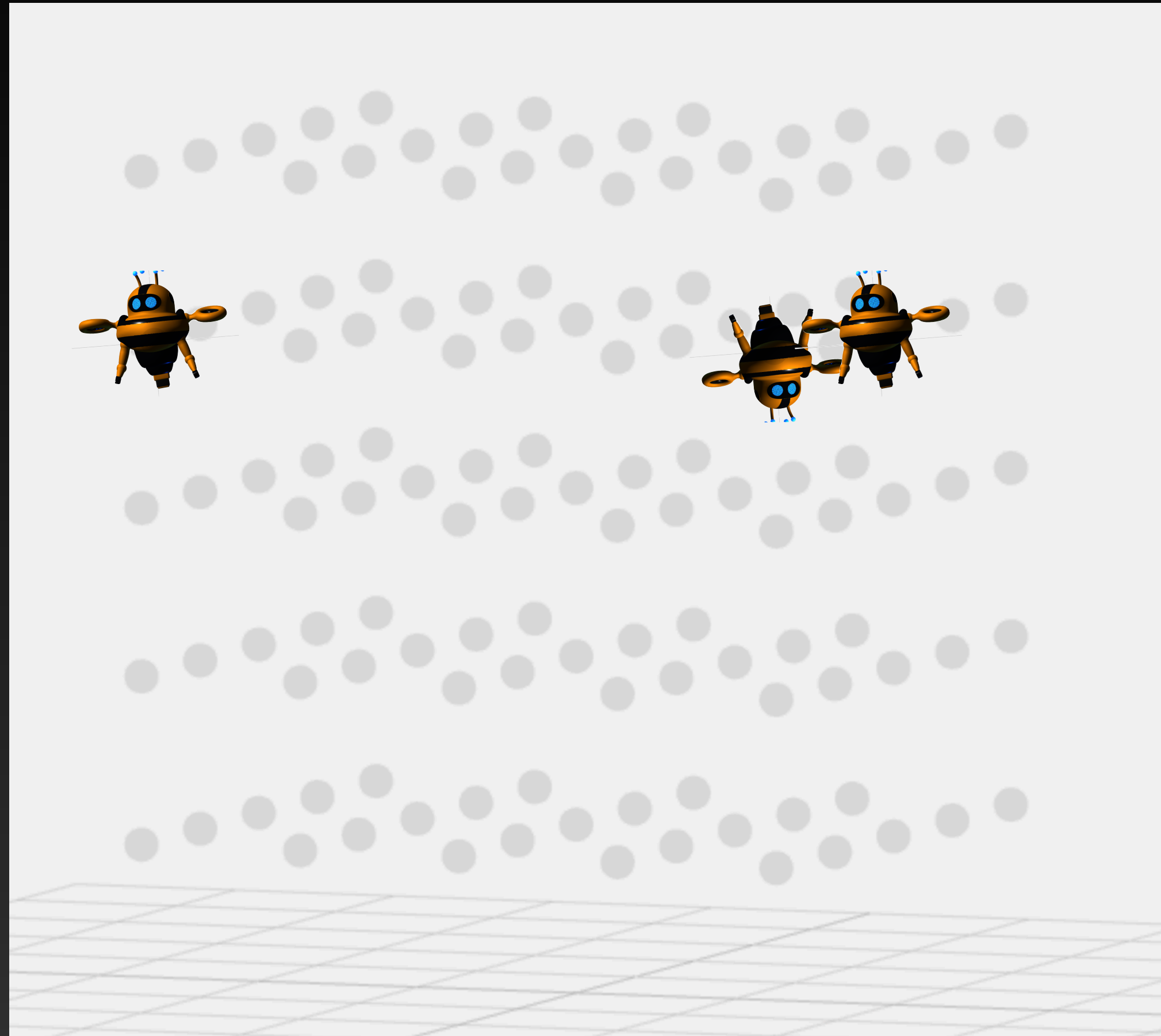


- looking good
- right for line-up
- doing fine
- Ok you can do it



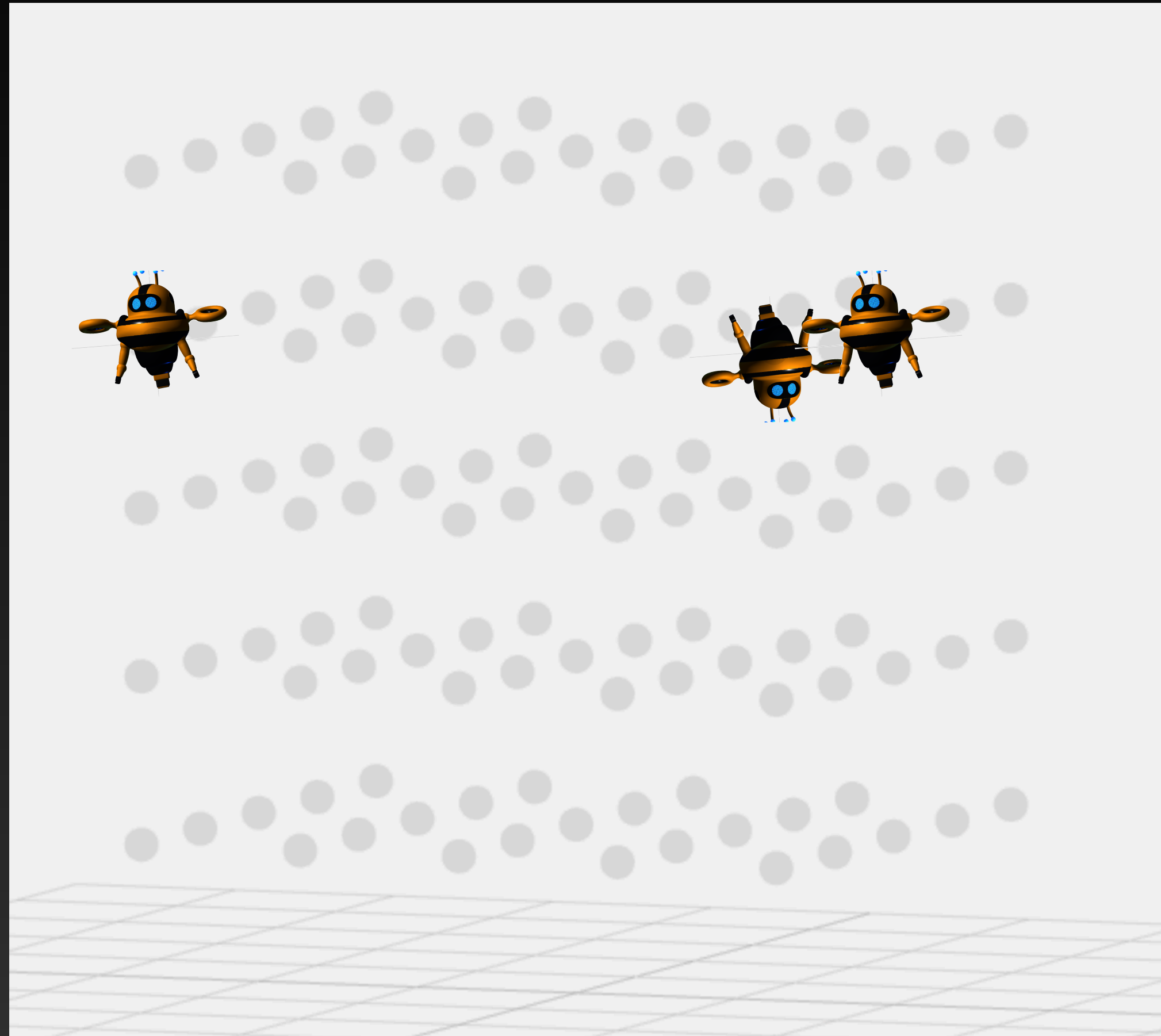
The Beedroid Model

The Beedroid Model



- Limited Visibility
- No memory
- No communication
- No consistent orientation
- Synchronous

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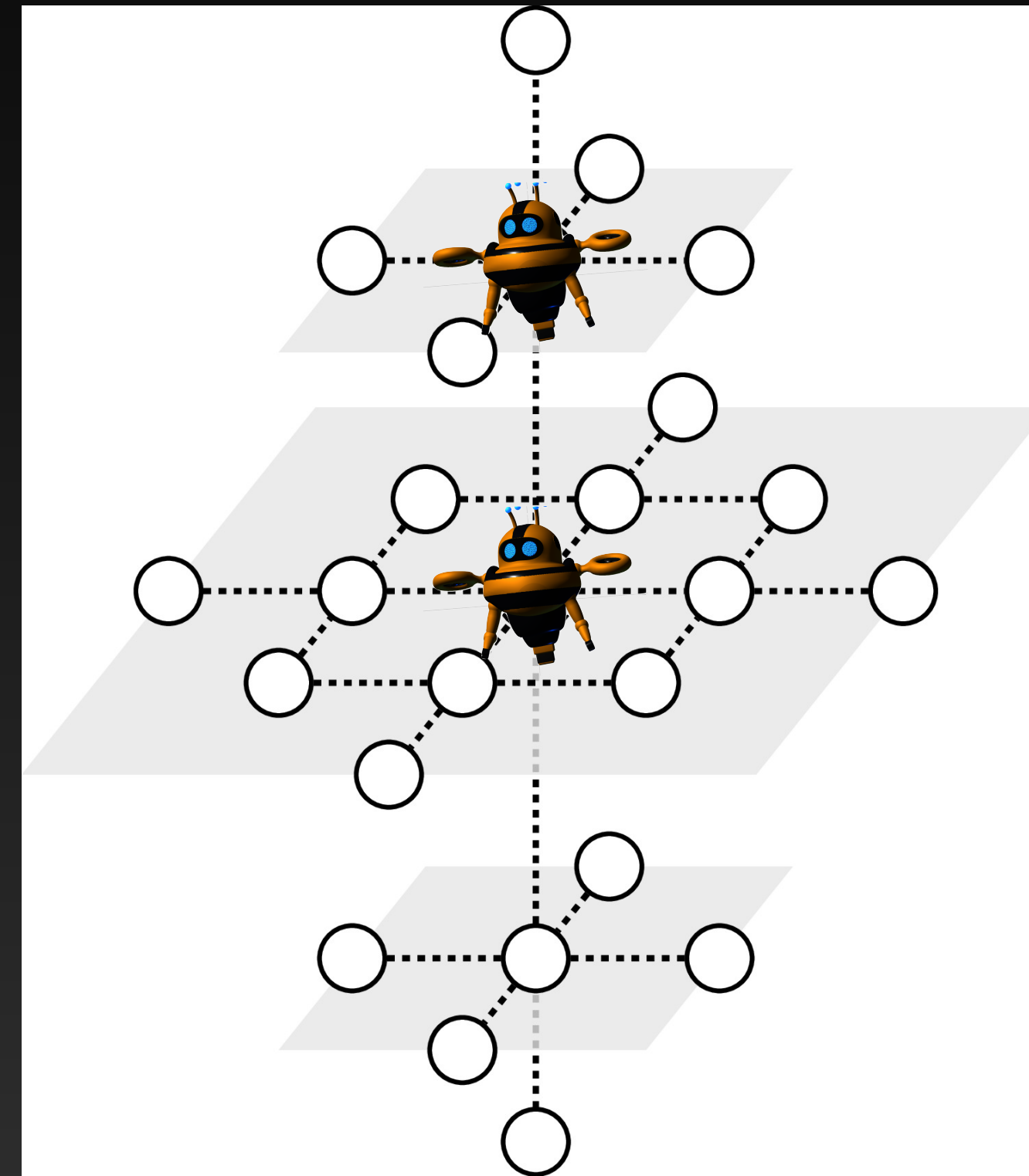
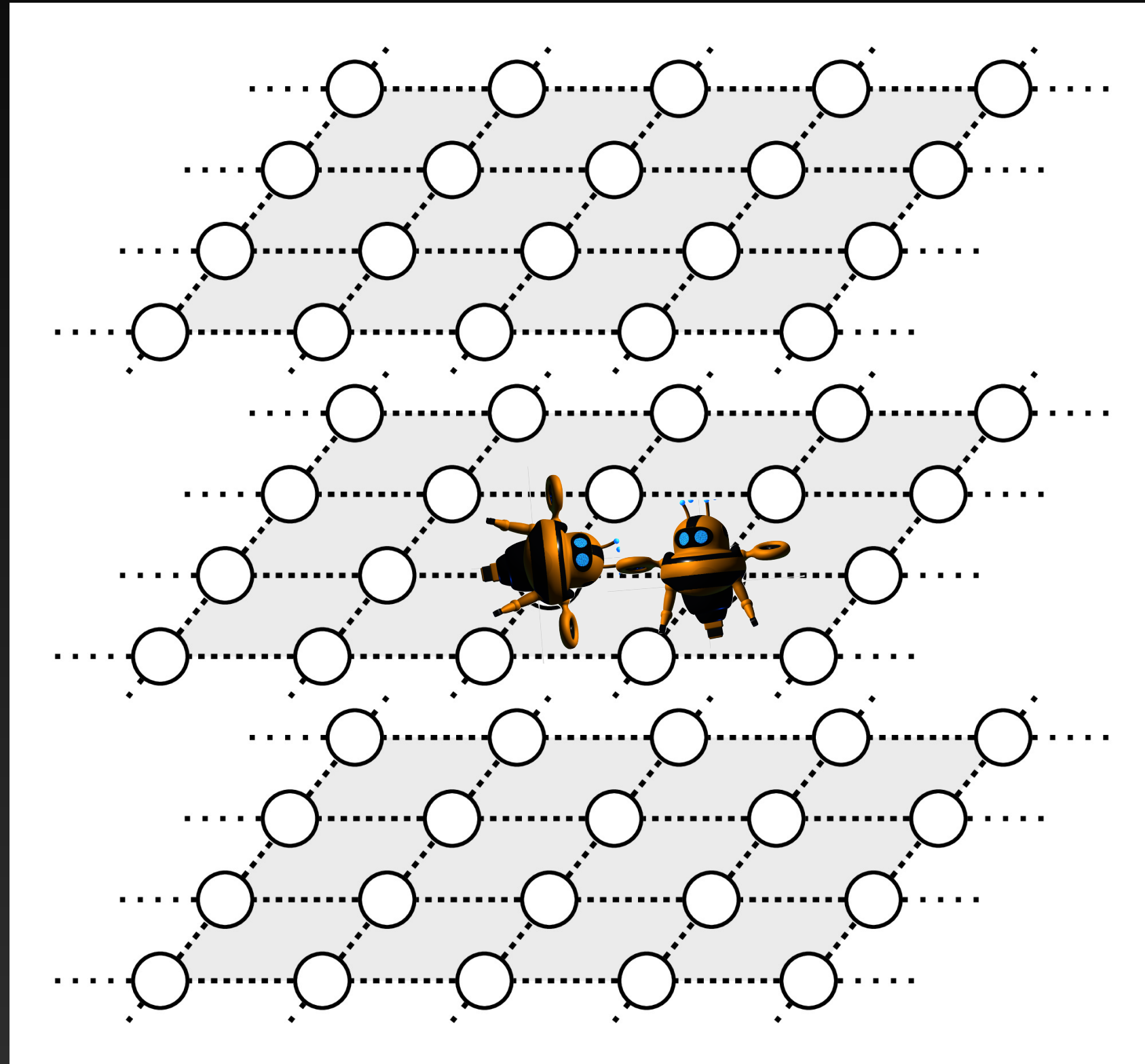
They execute cycles:

- Look
- Compute
- Move

Goal: Explore the 3D grid

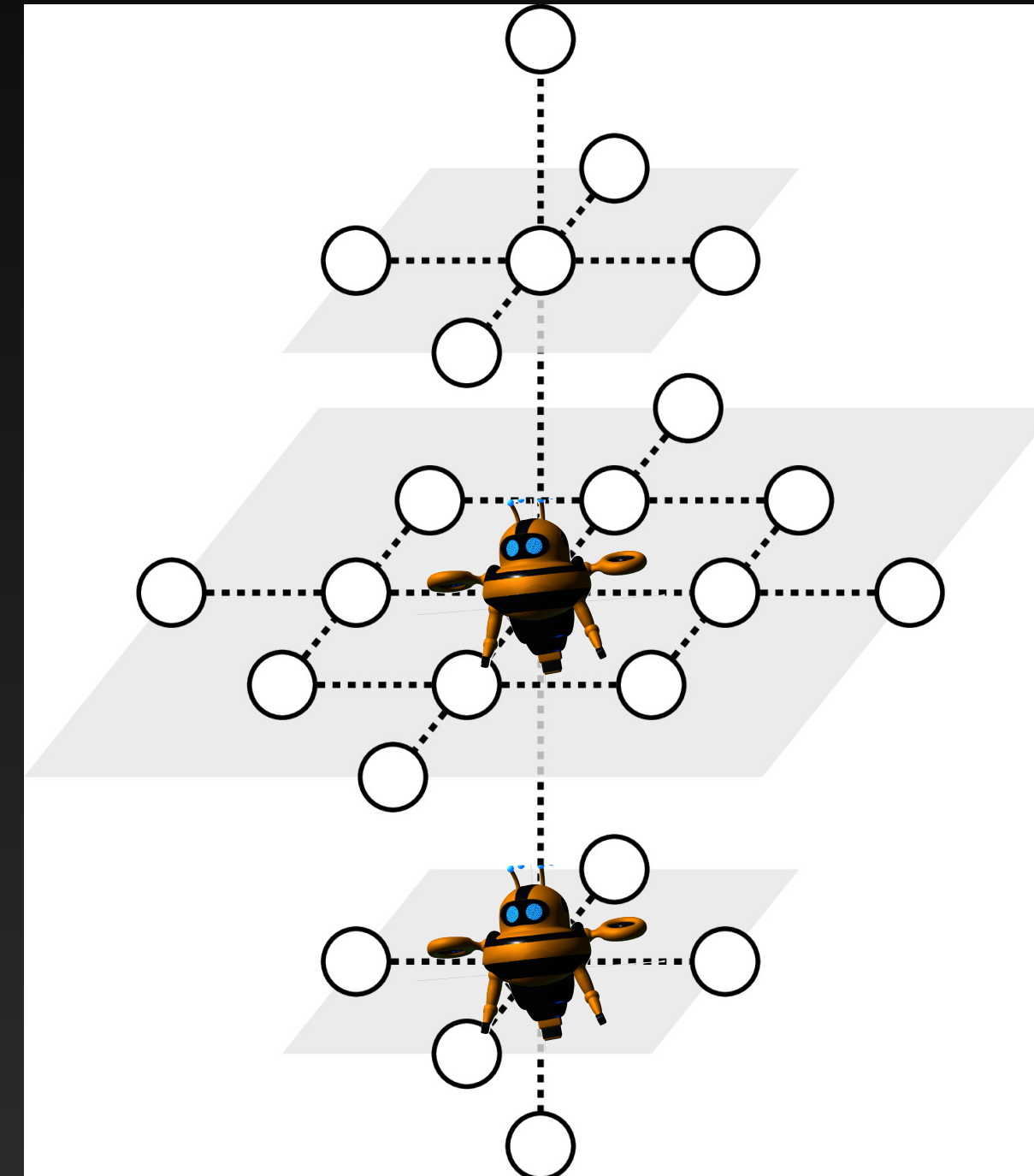
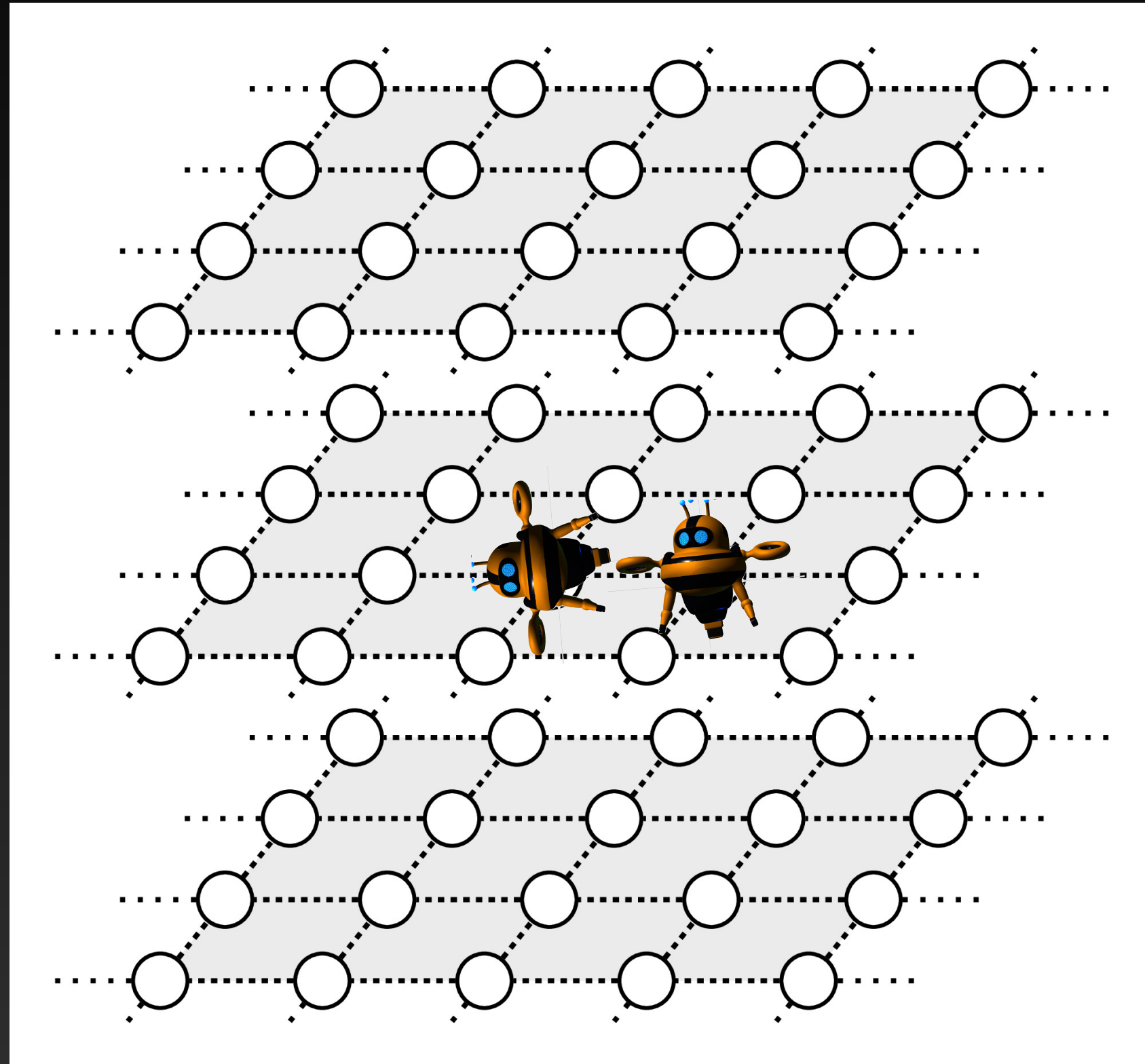
The Beedroid Model

Look phase



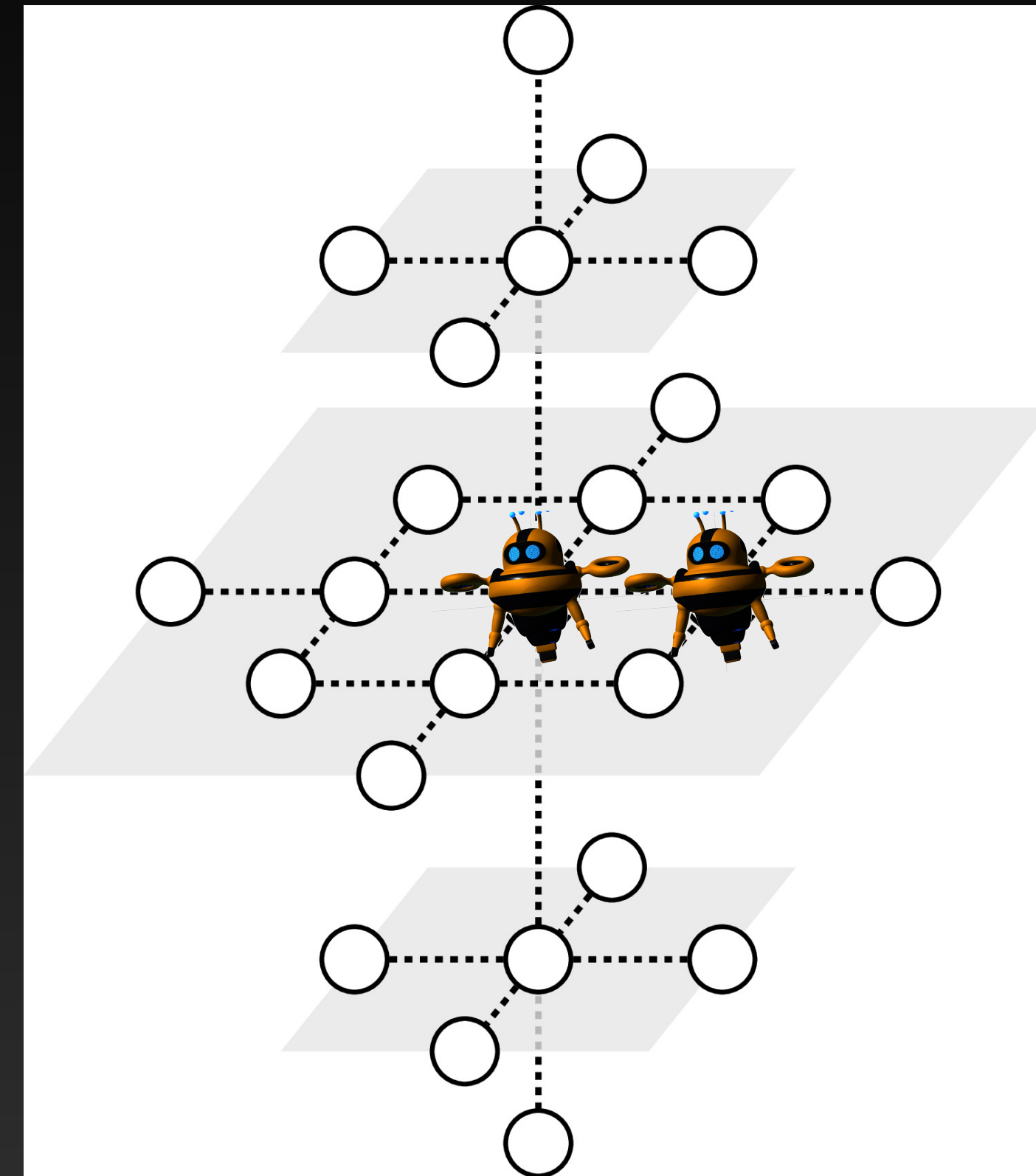
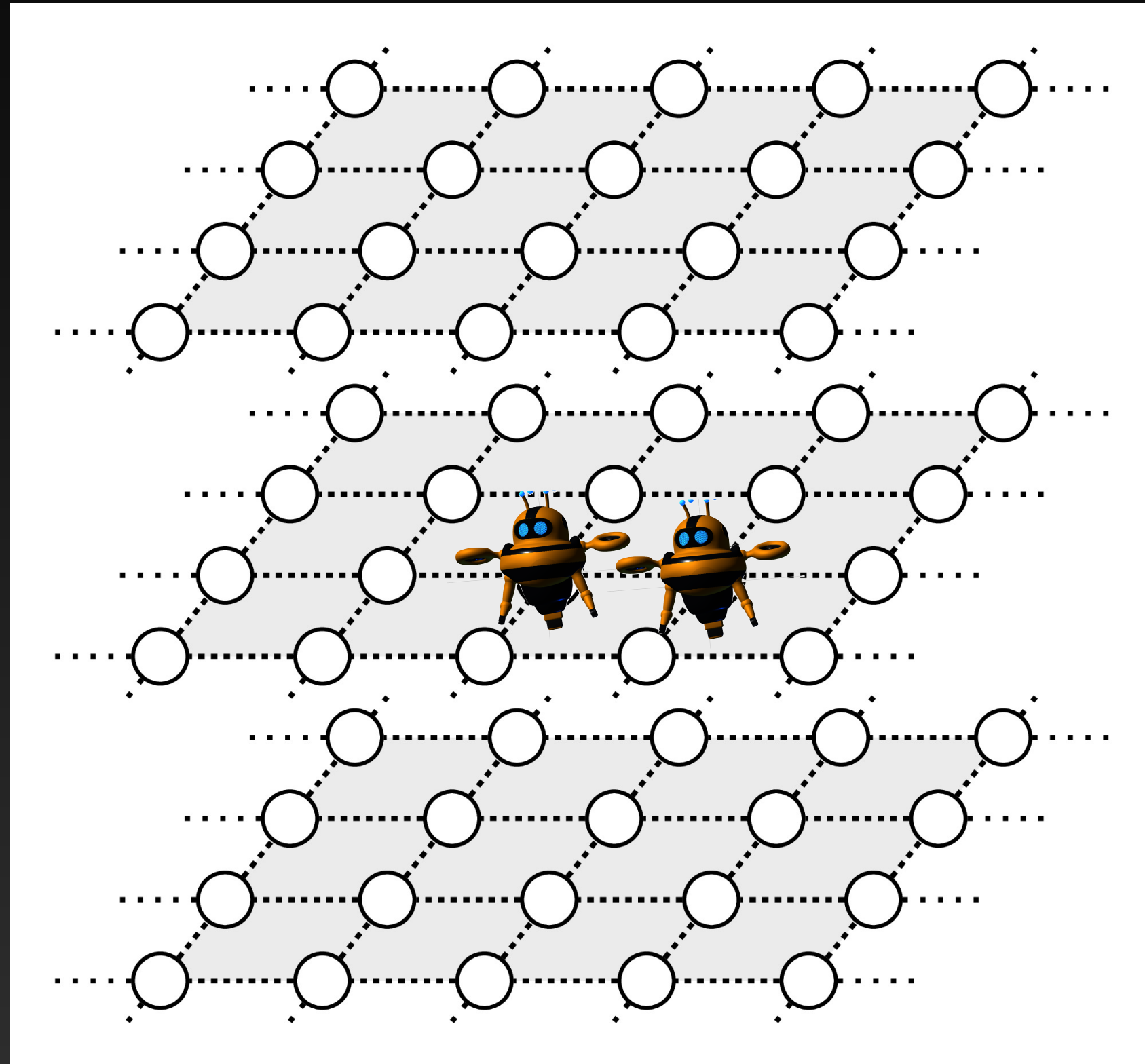
The Beedroid Model

Look phase



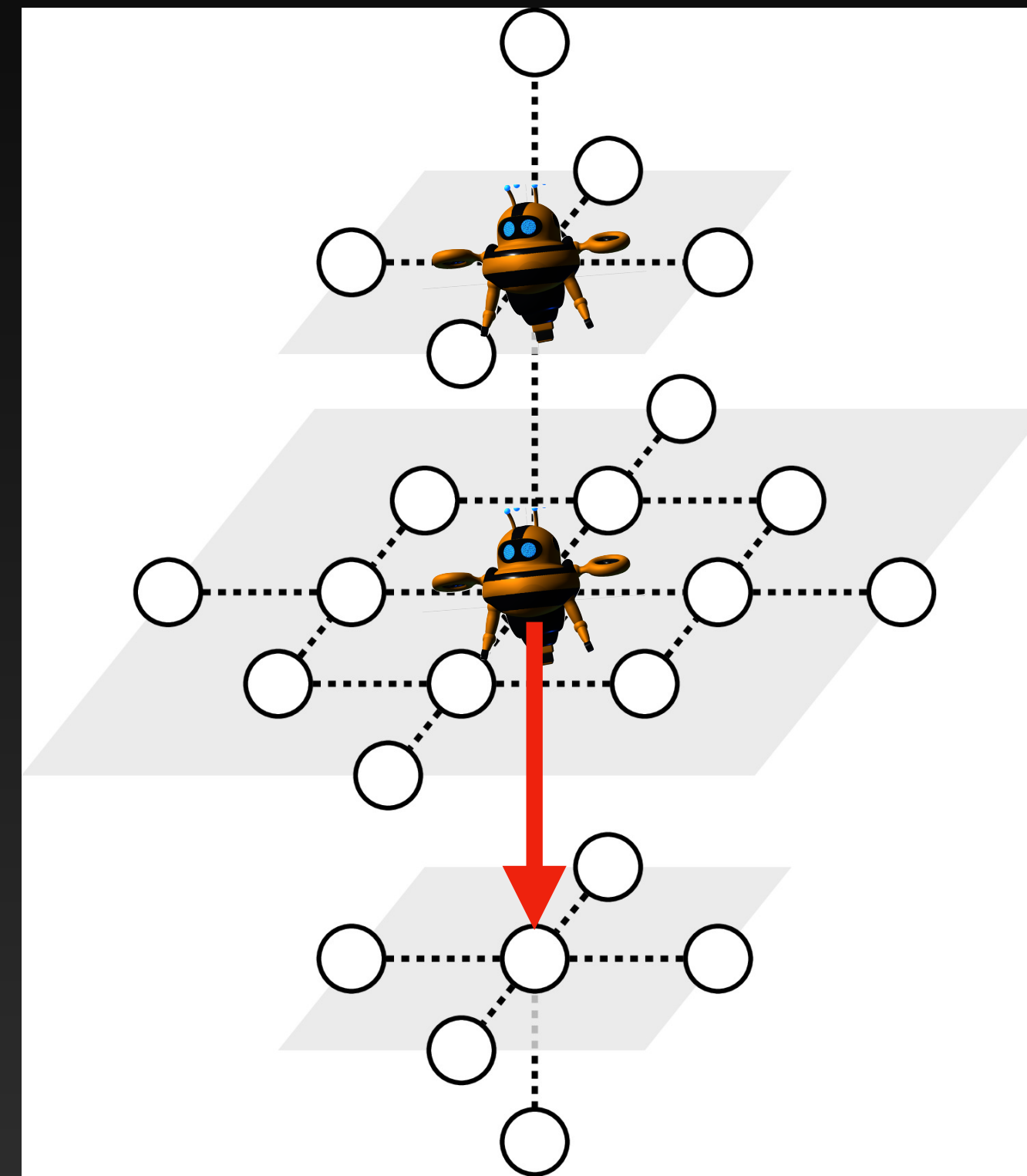
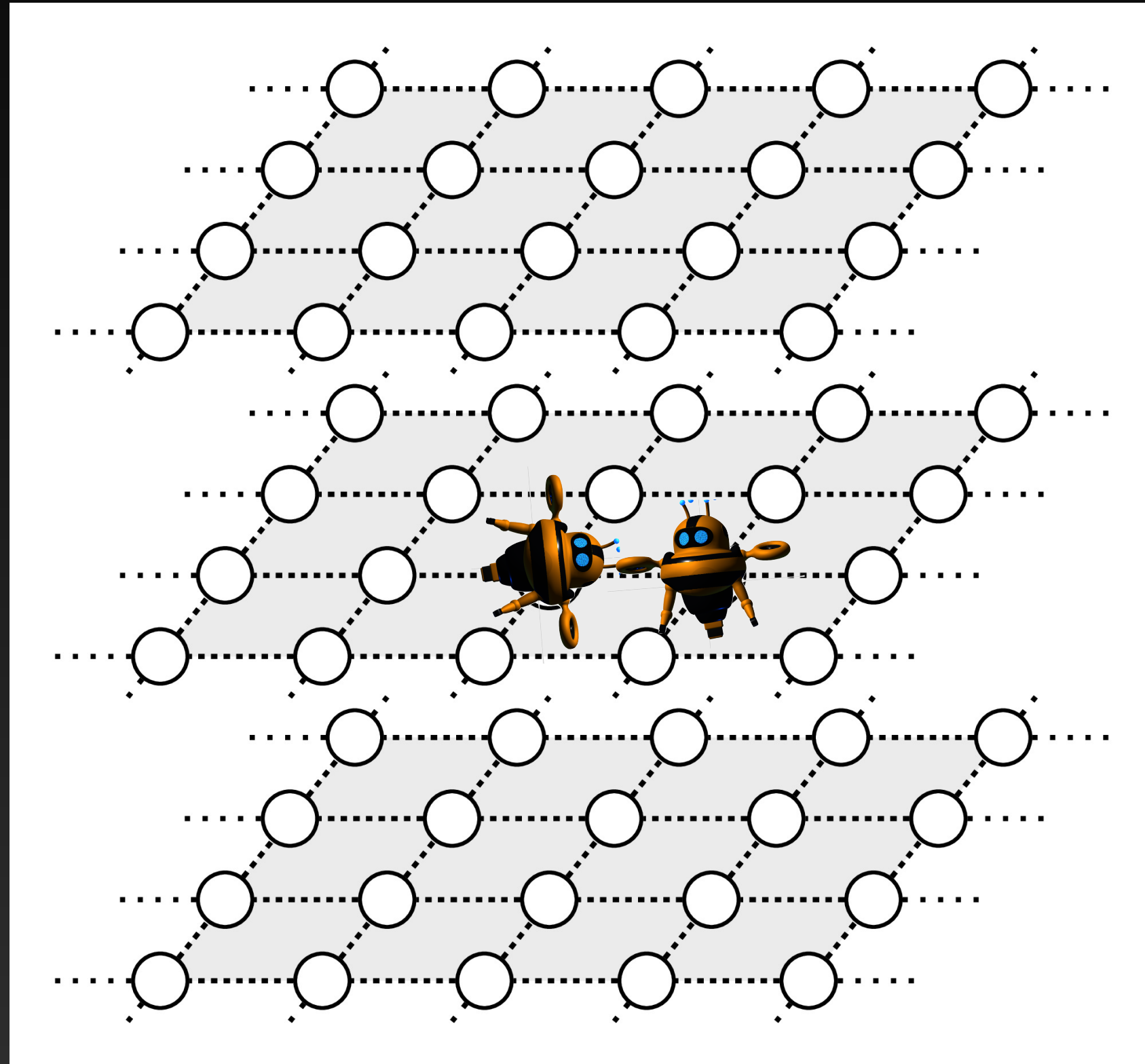
The Beedroid Model

Look phase



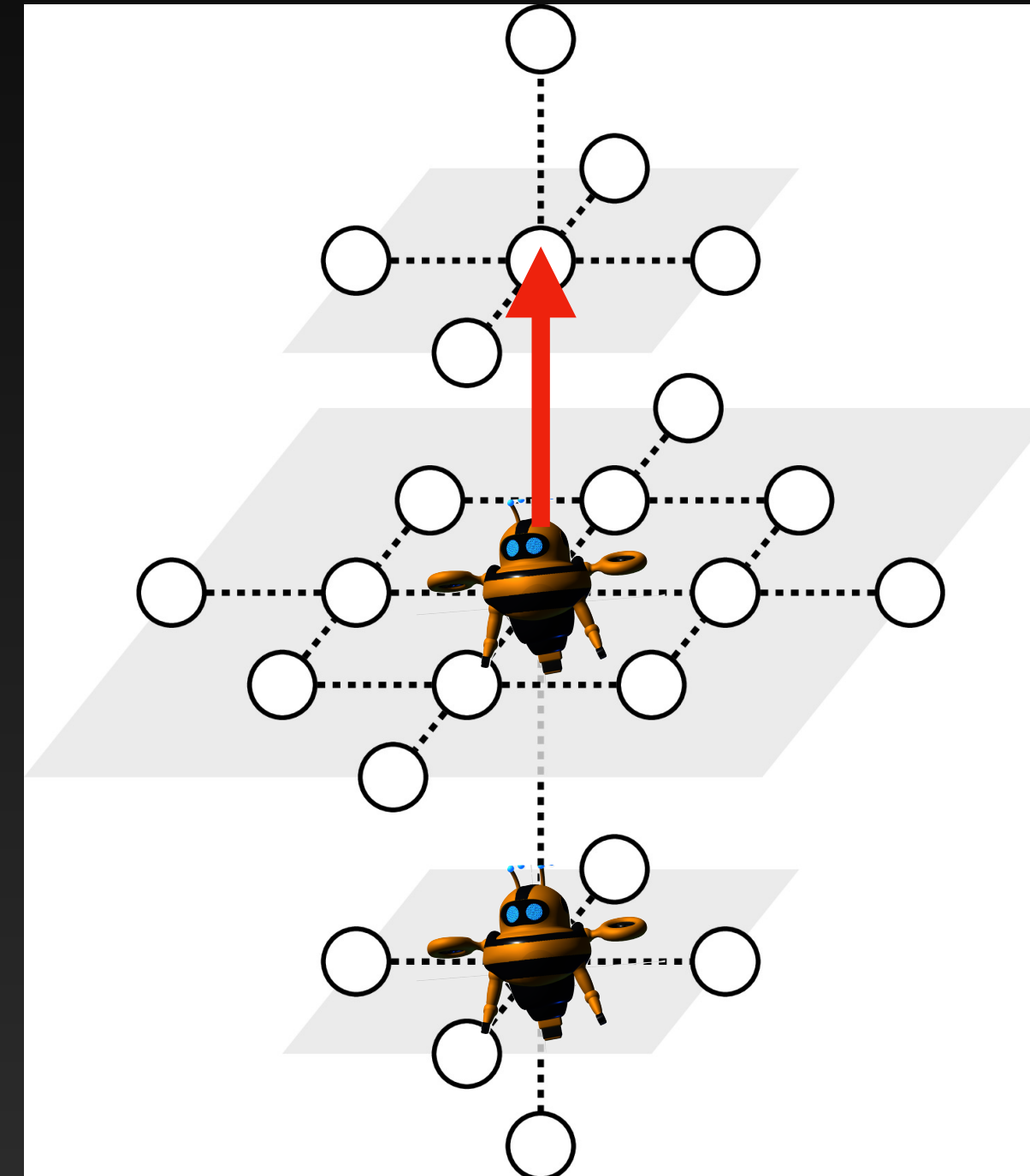
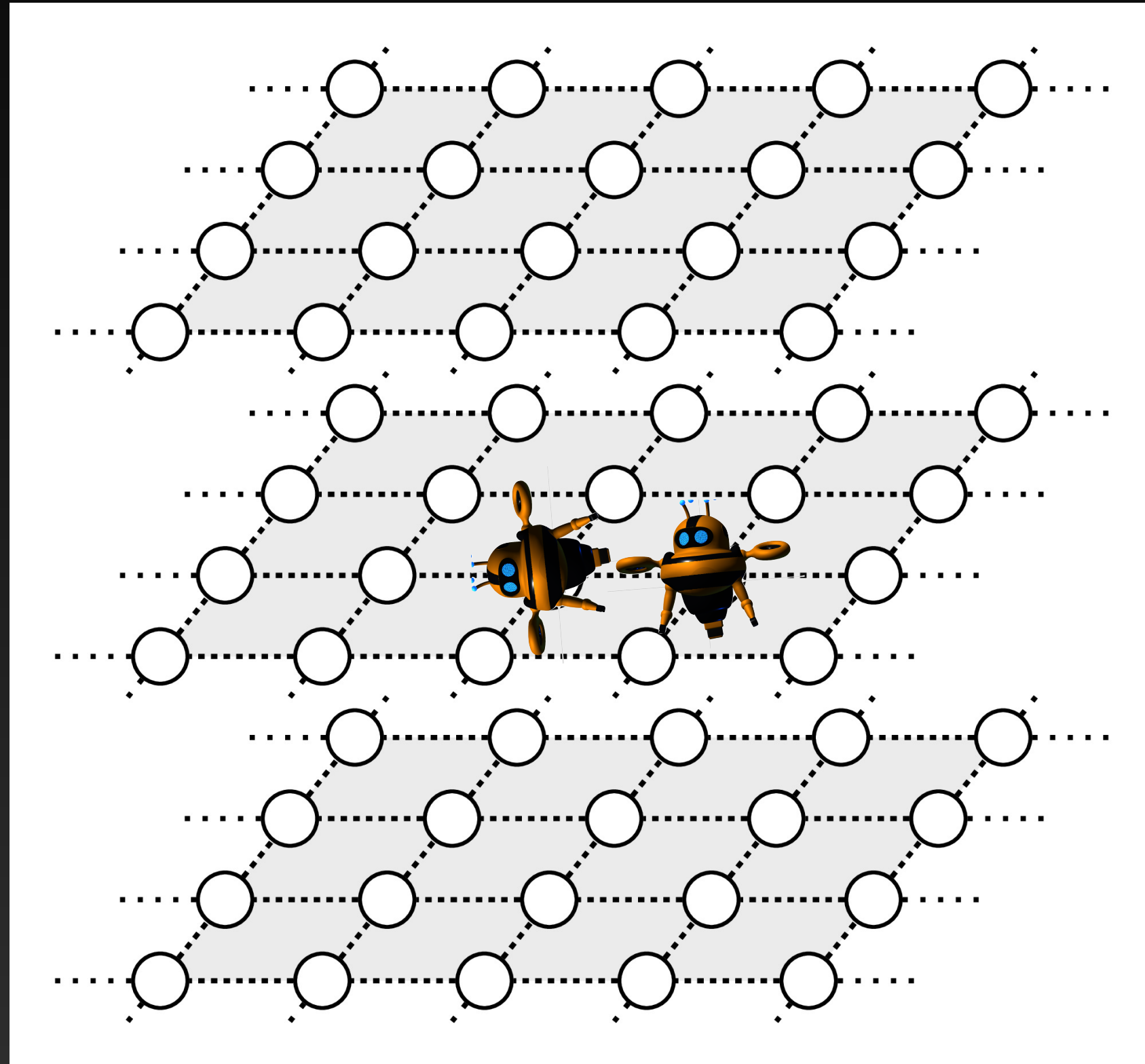
The Beedroid Model

Compute phase



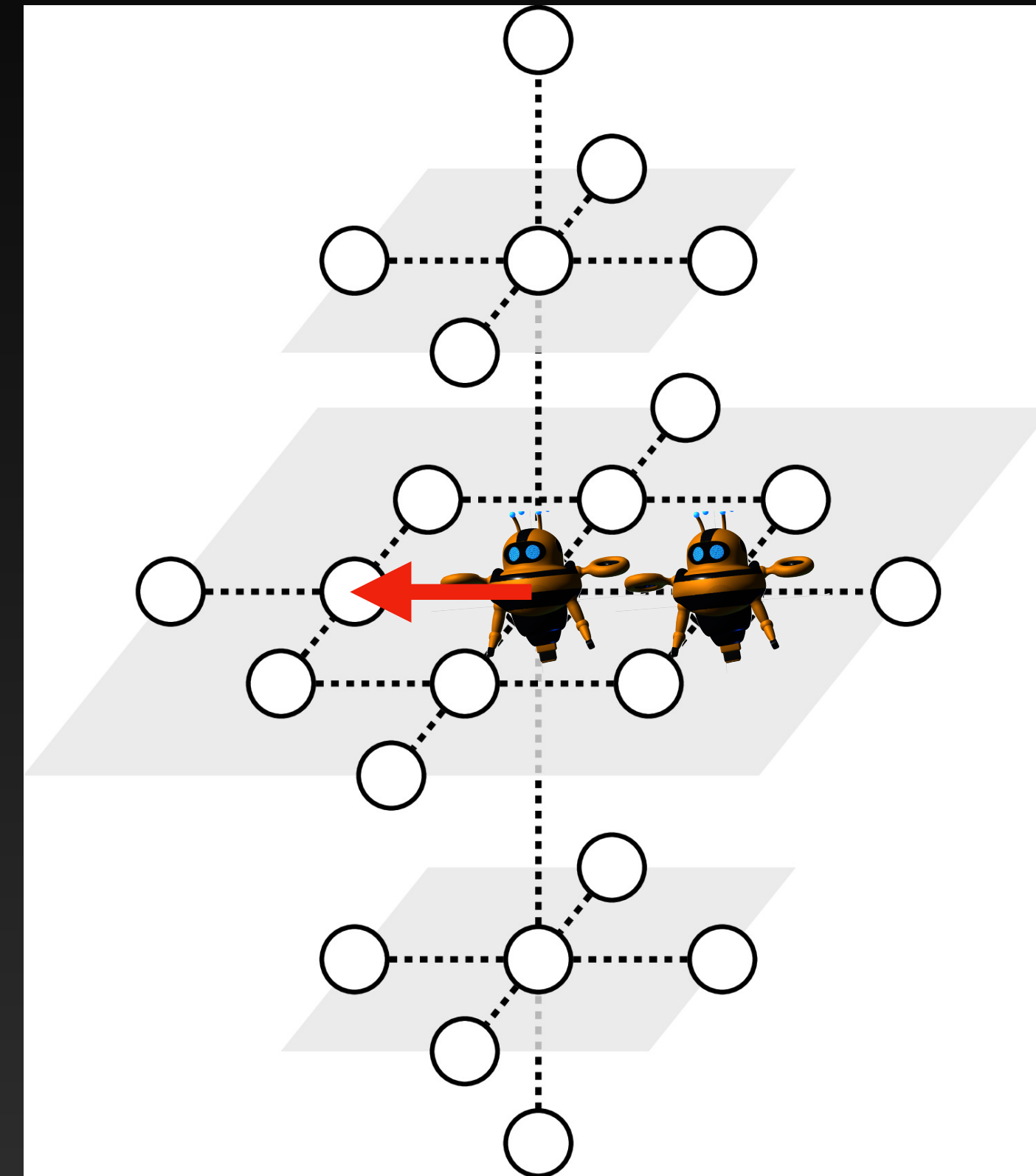
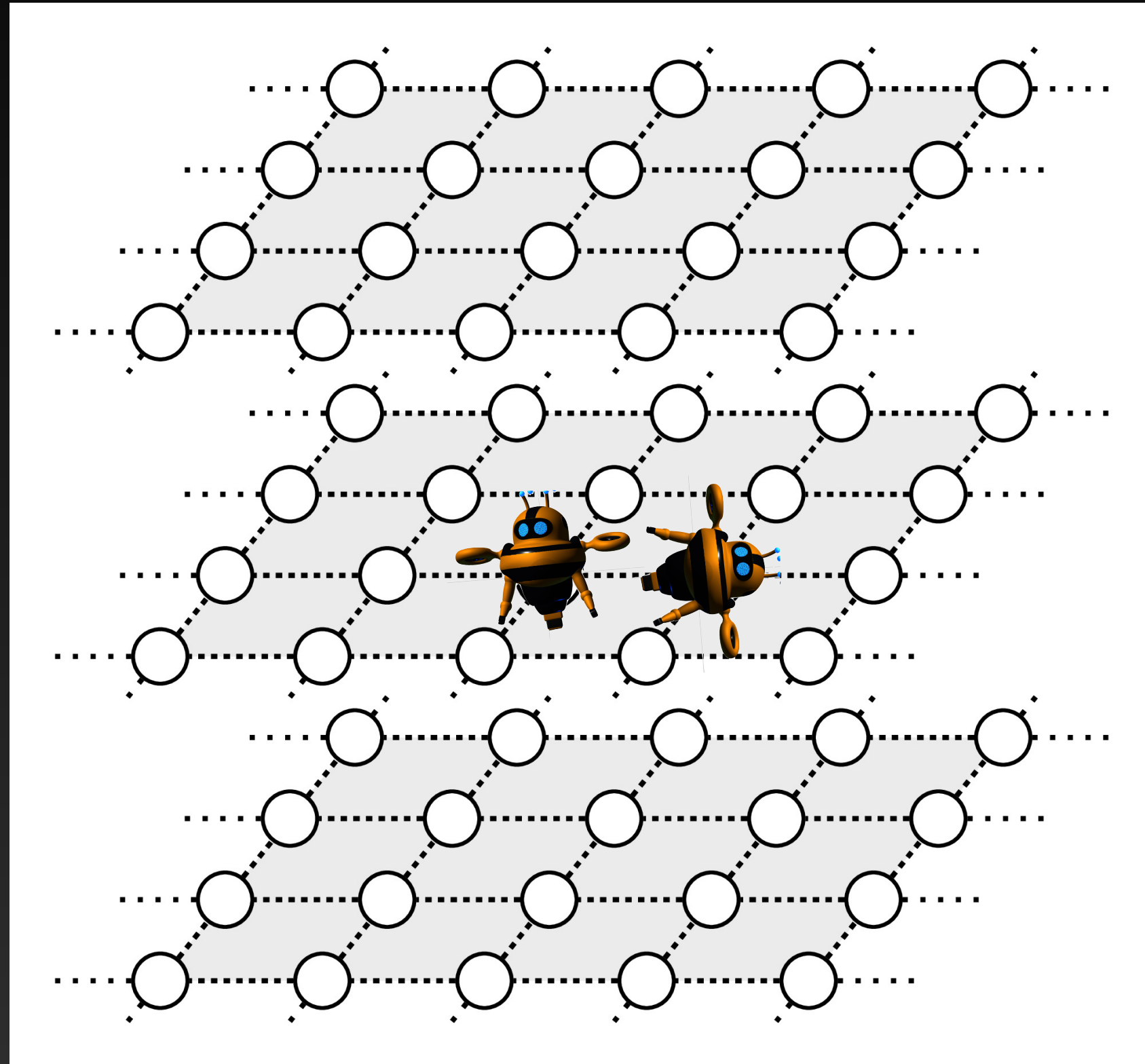
The Beedroid Model

Compute phase



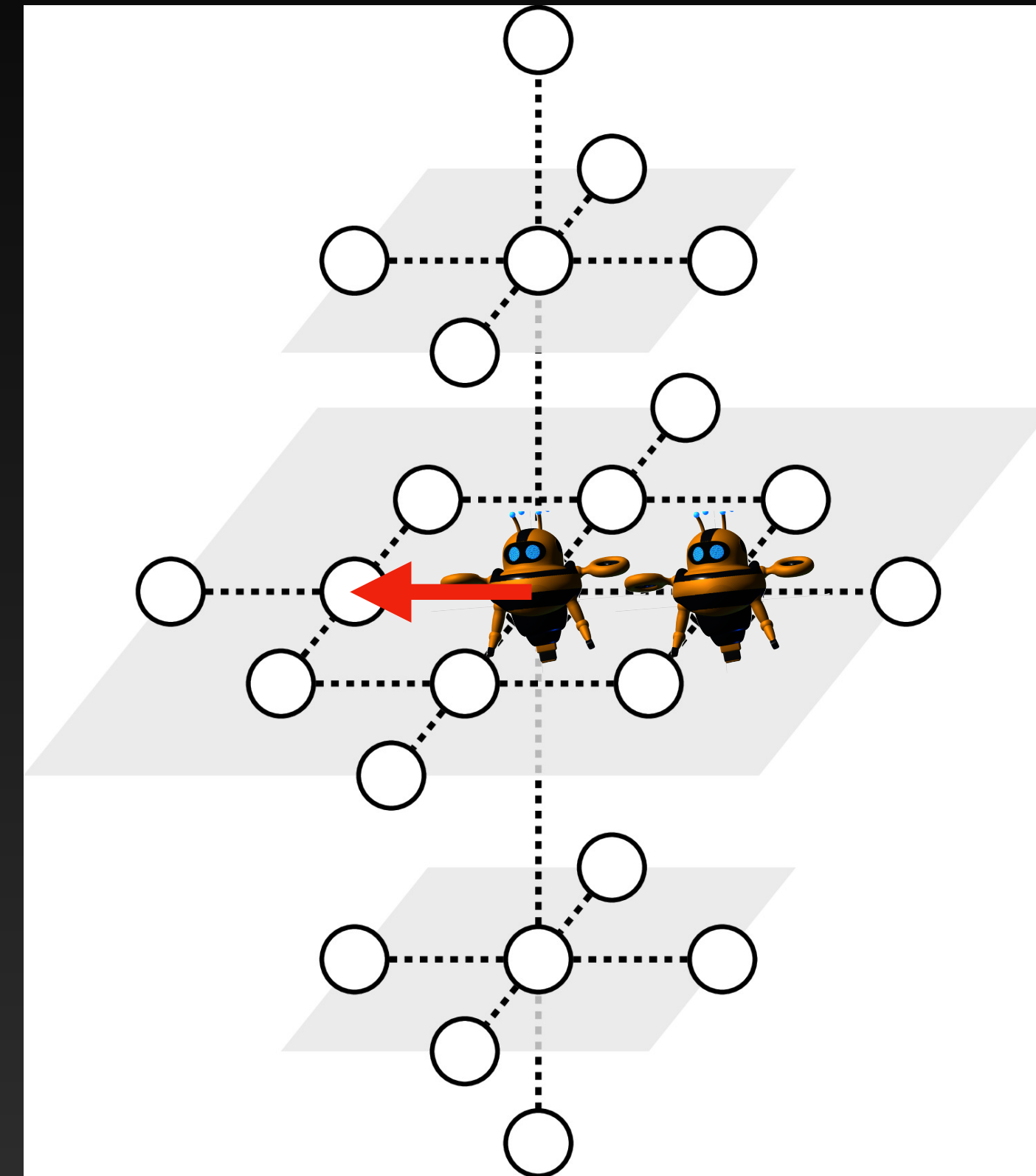
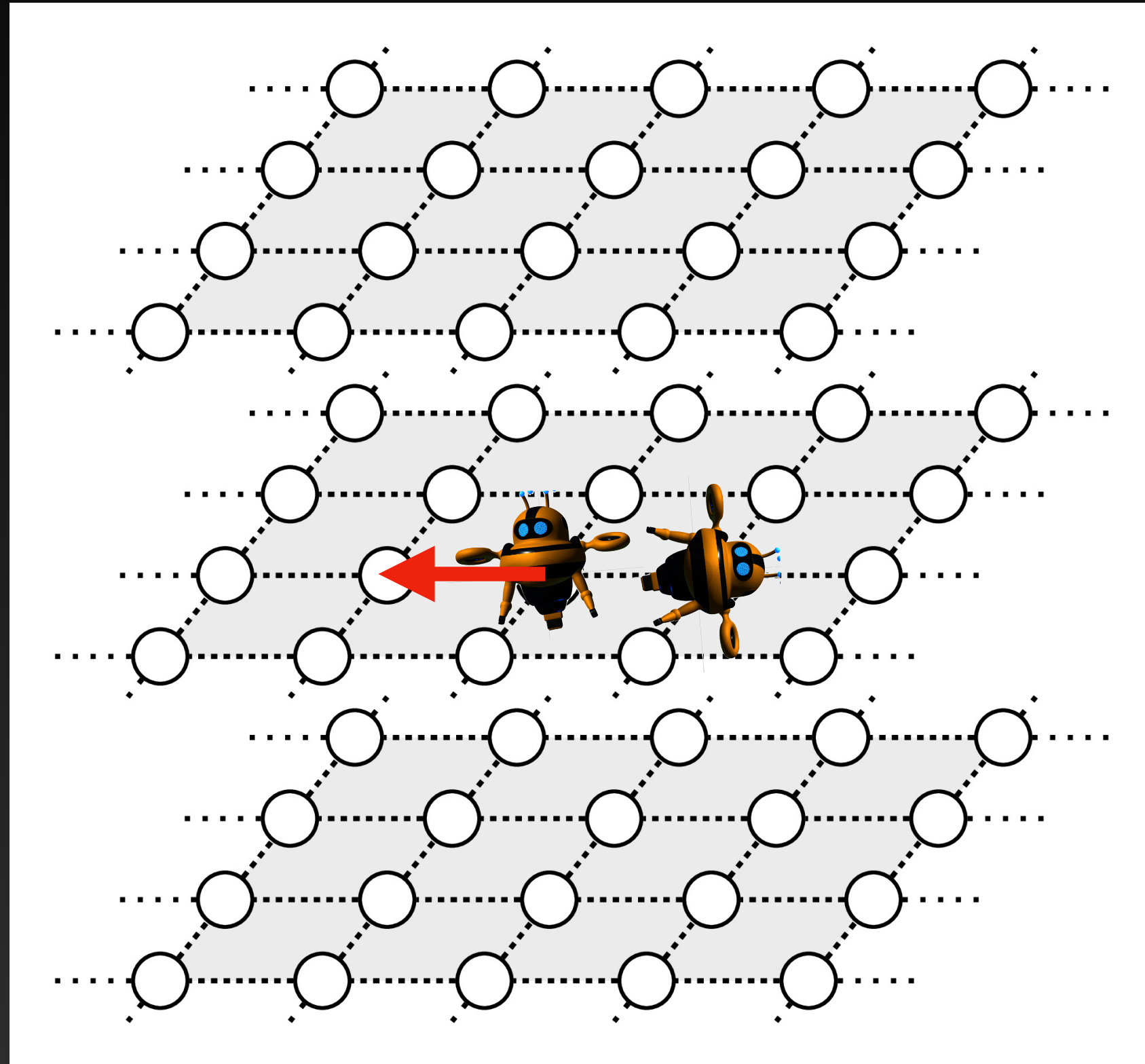
The Beedroid Model

Compute phase



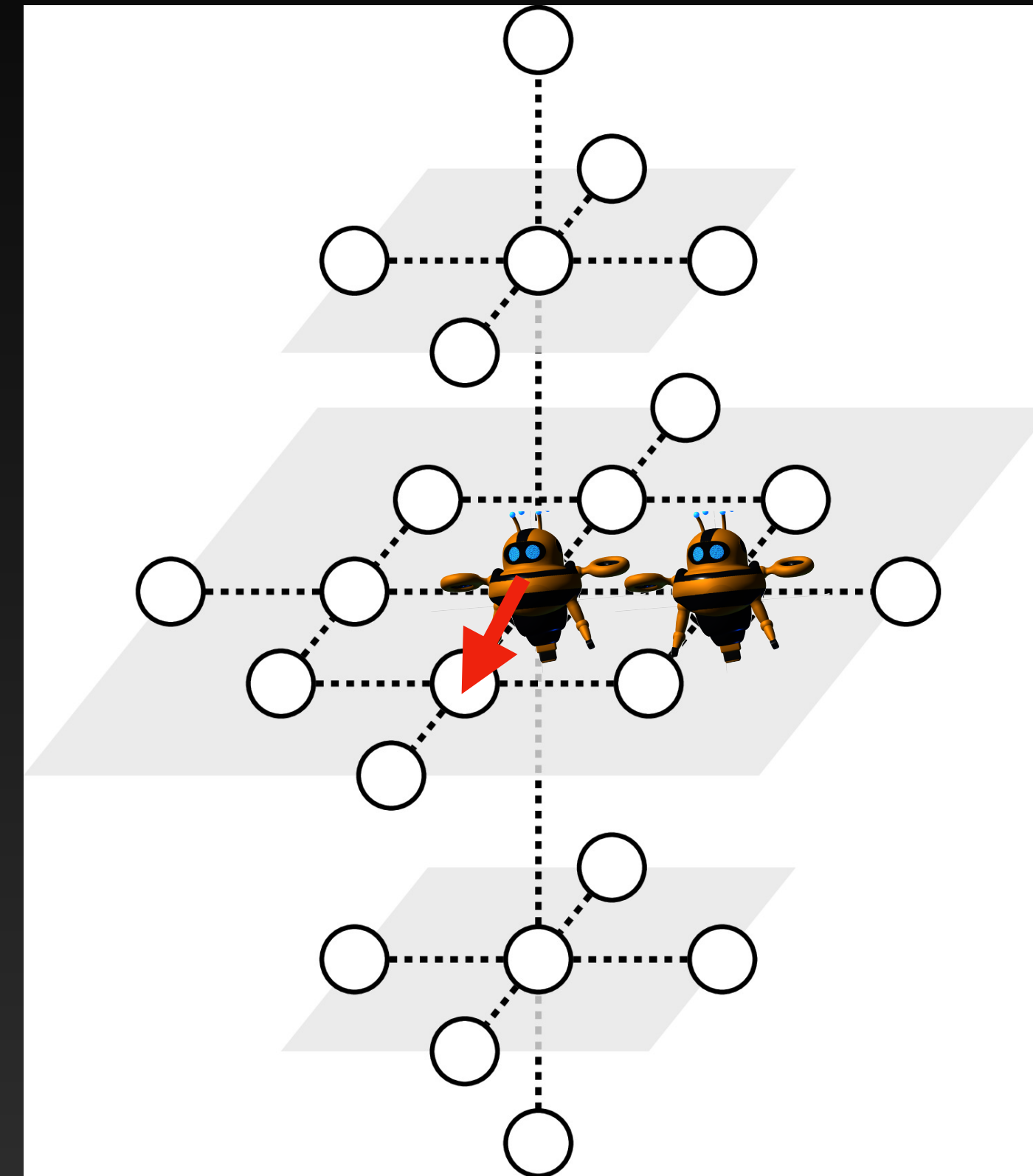
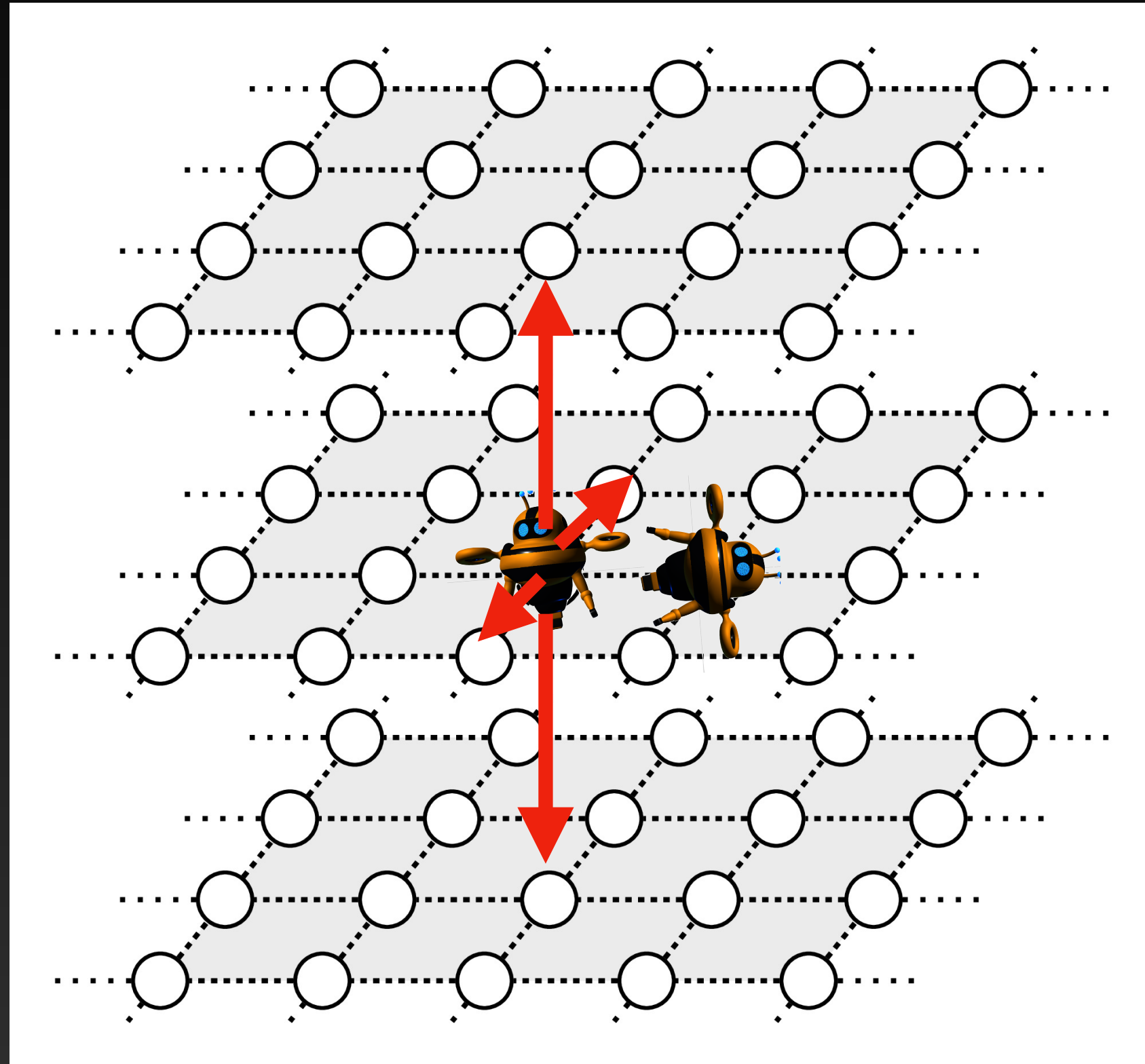
The Beedroid Model

Compute phase



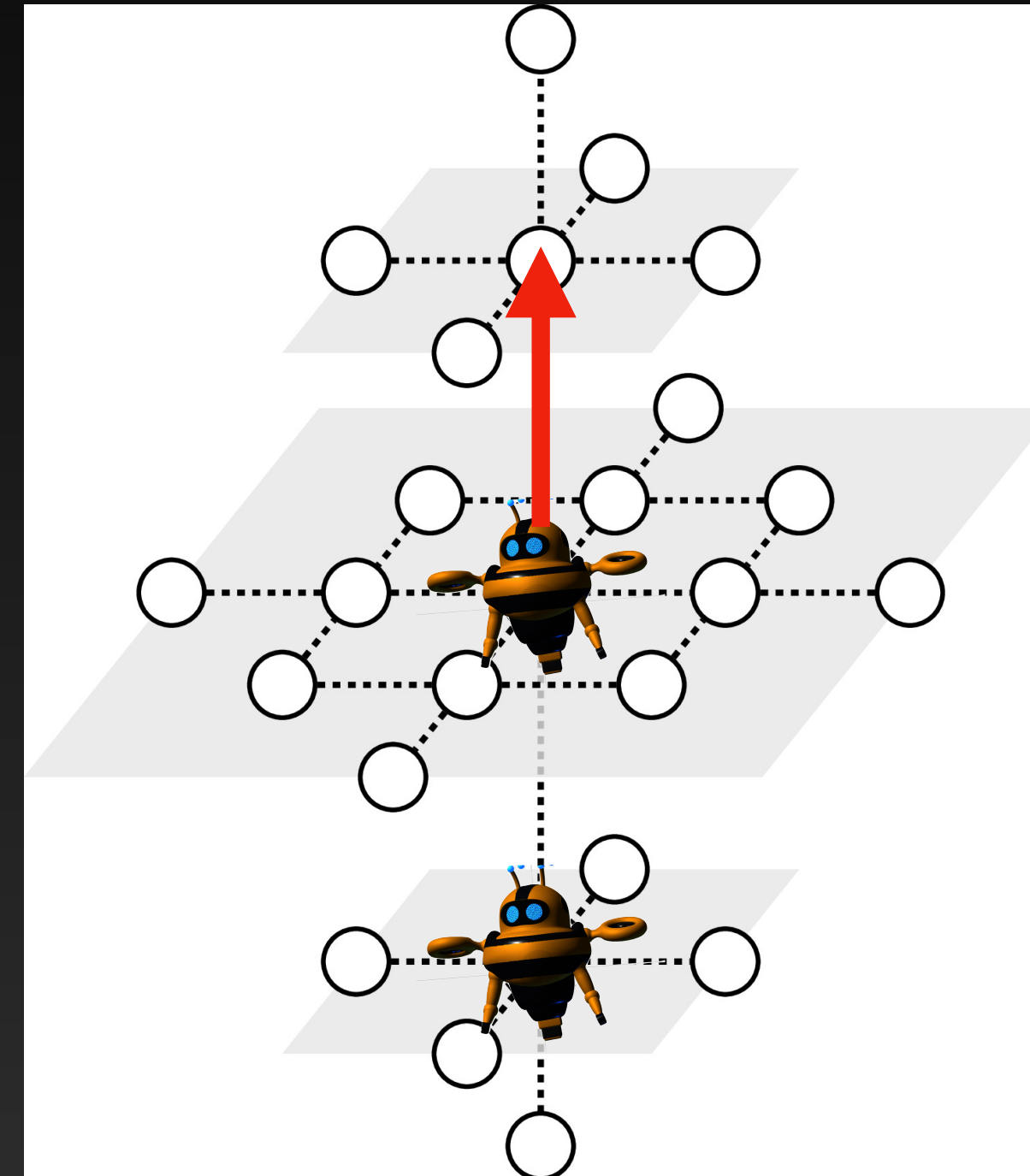
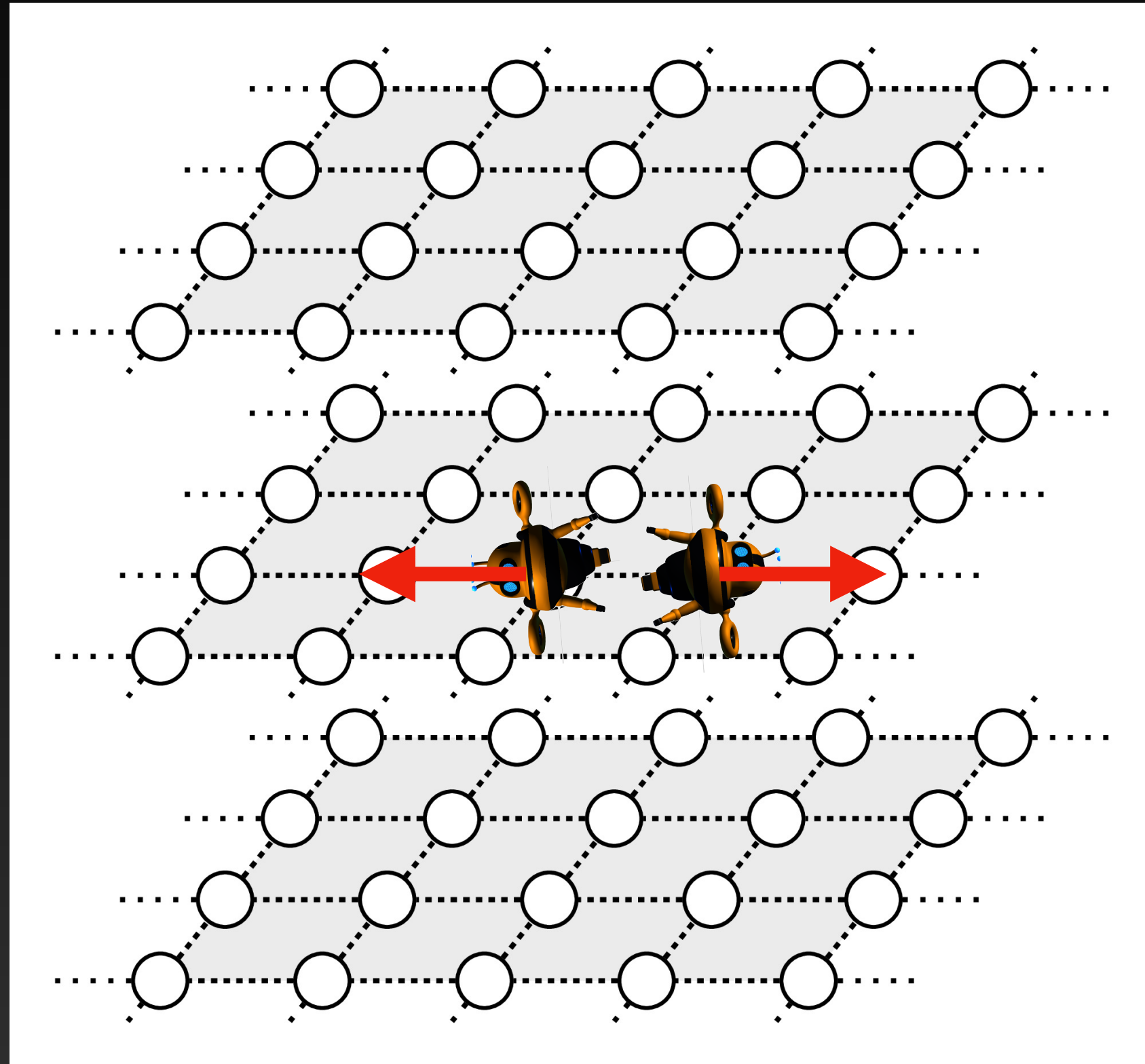
The Beedroid Model

Compute phase



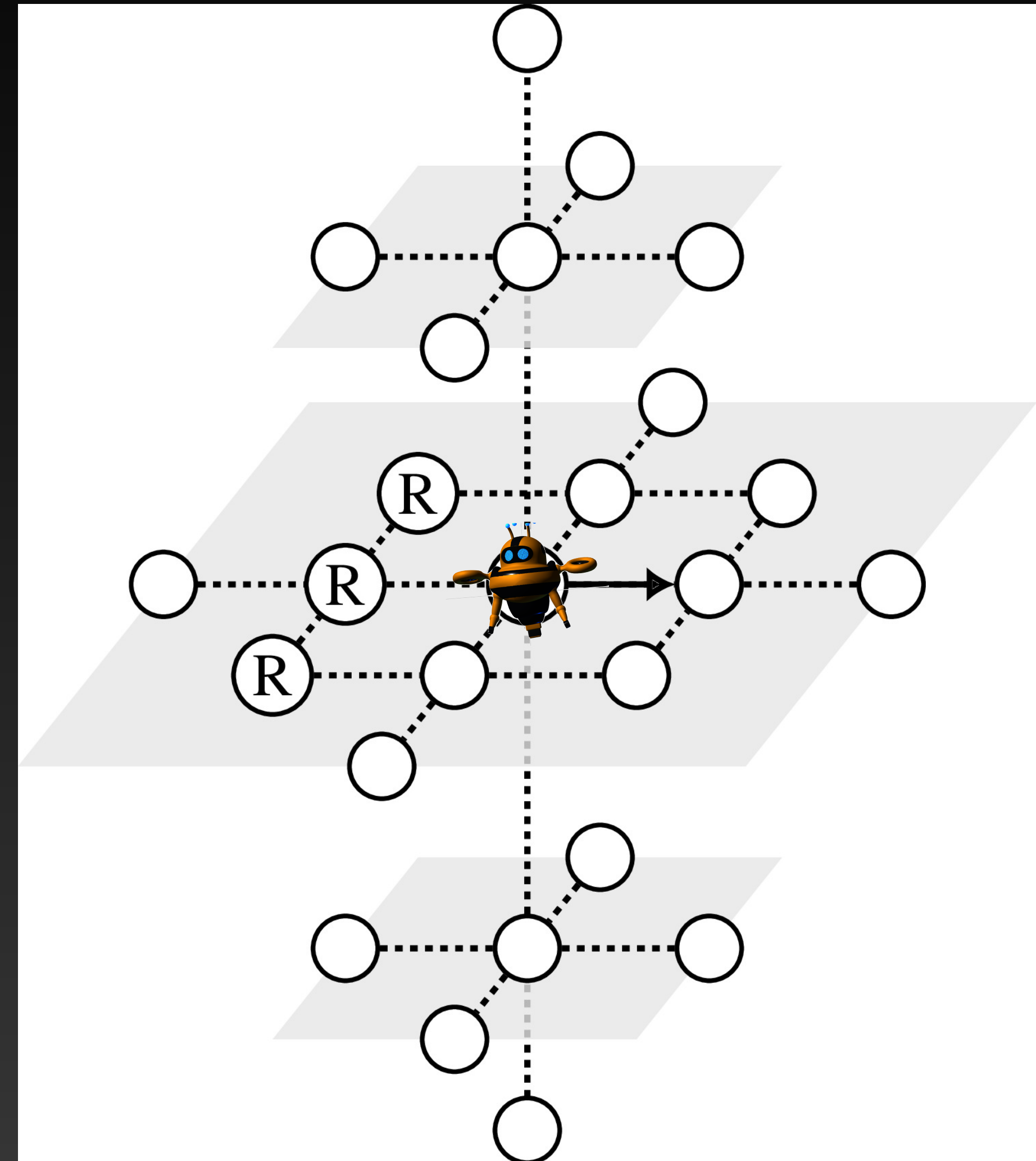
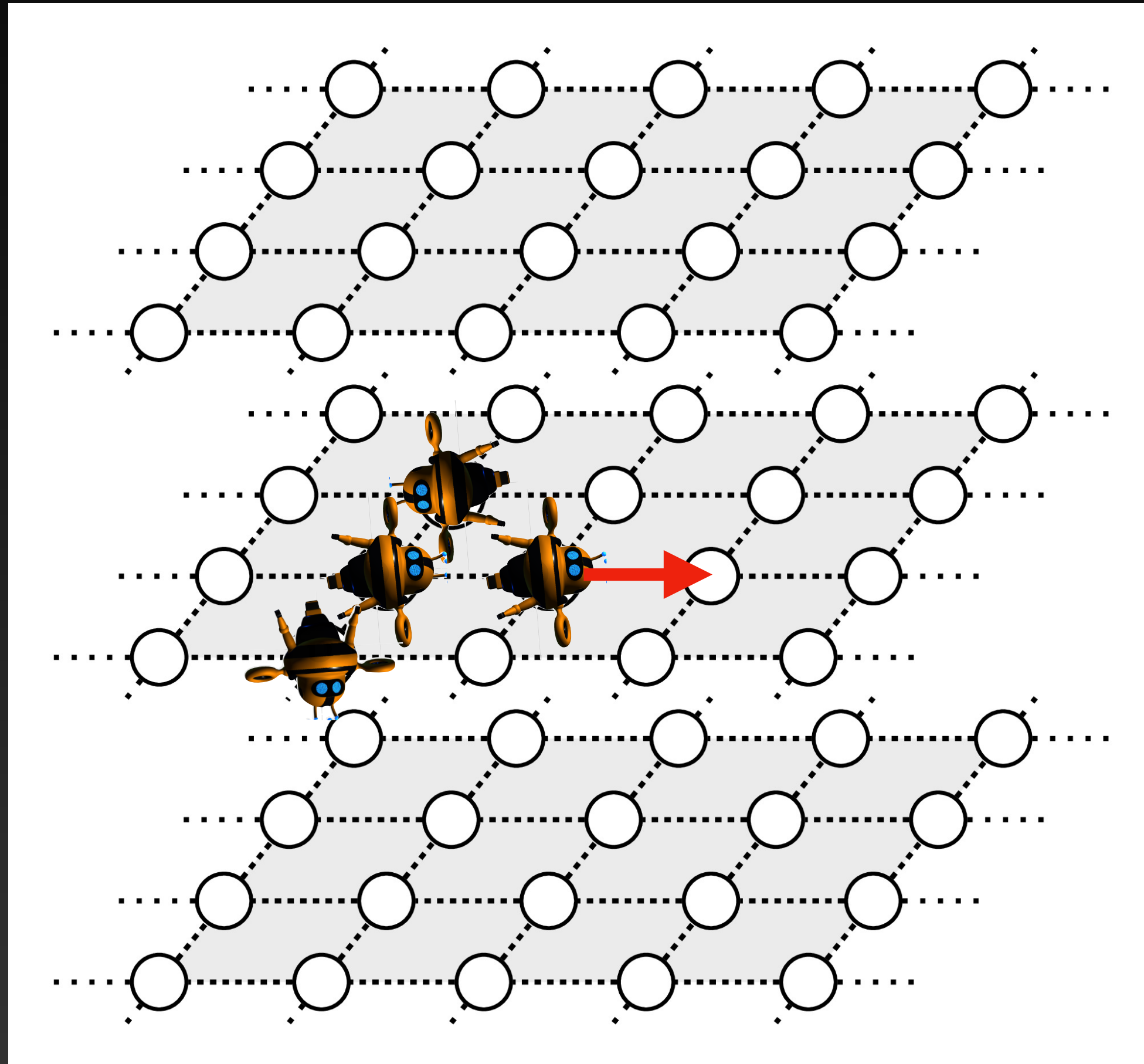
The Beedroid Model

Move phase

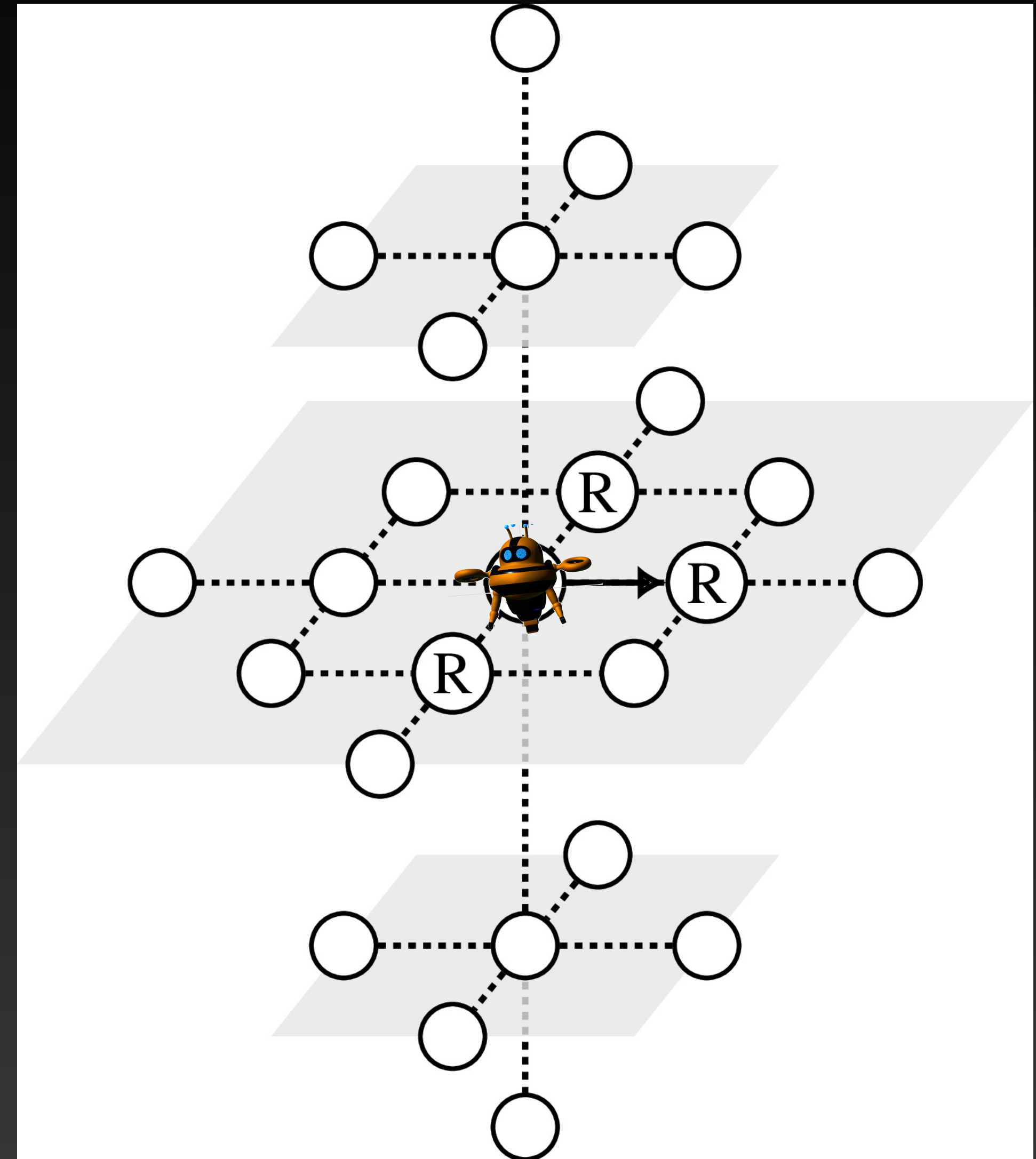
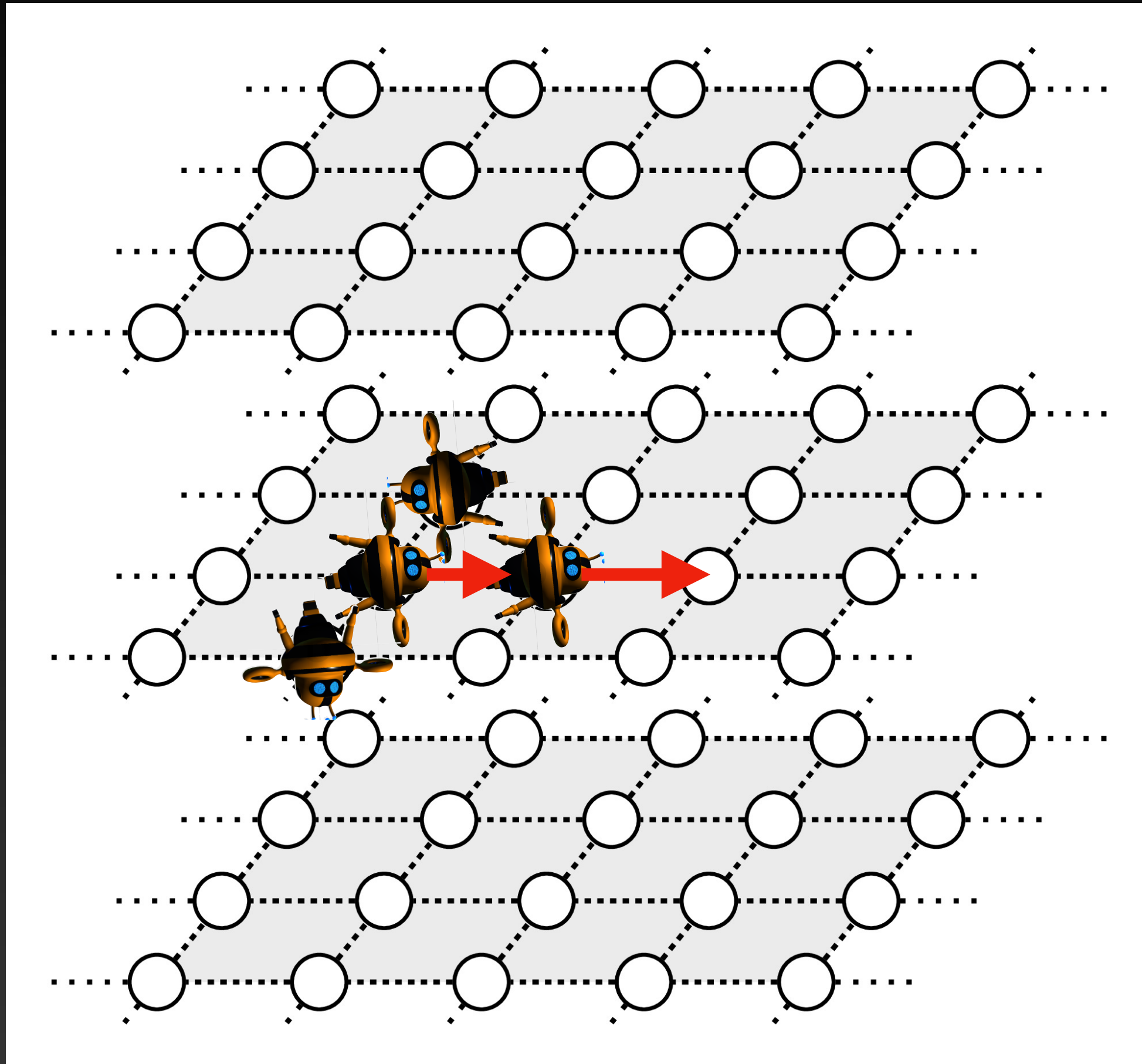


How to move straight

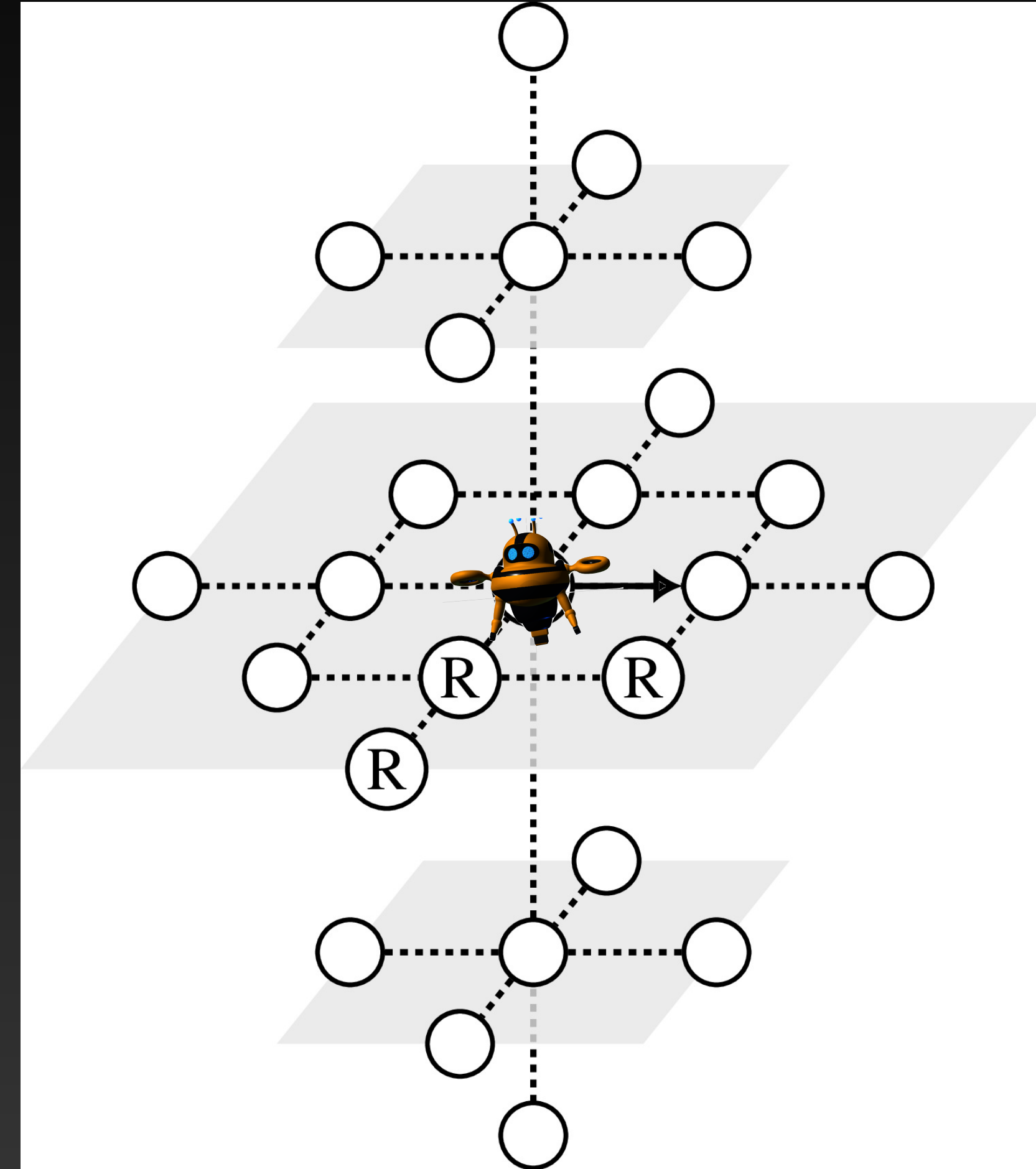
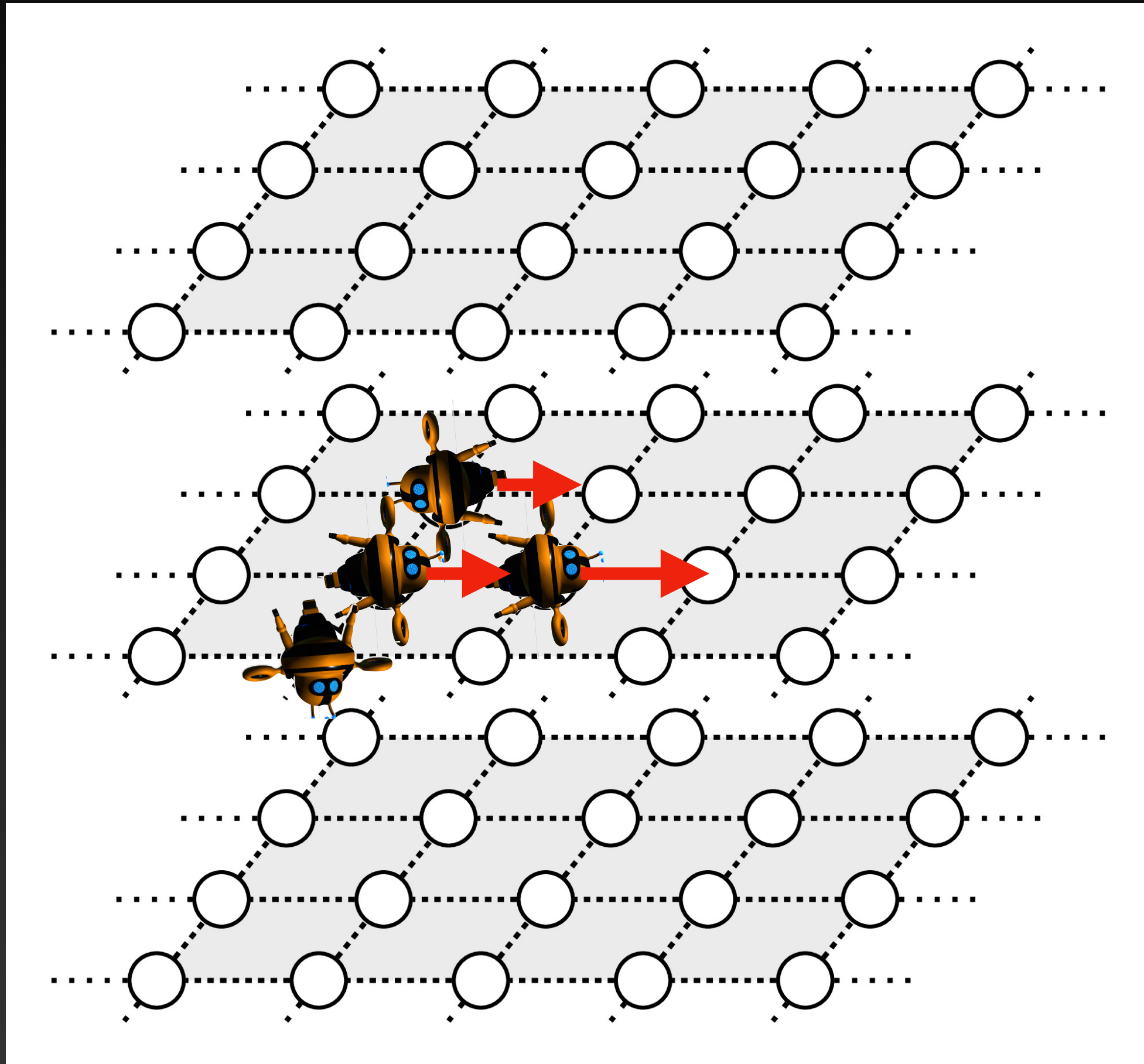
How to move straight



How to move straight

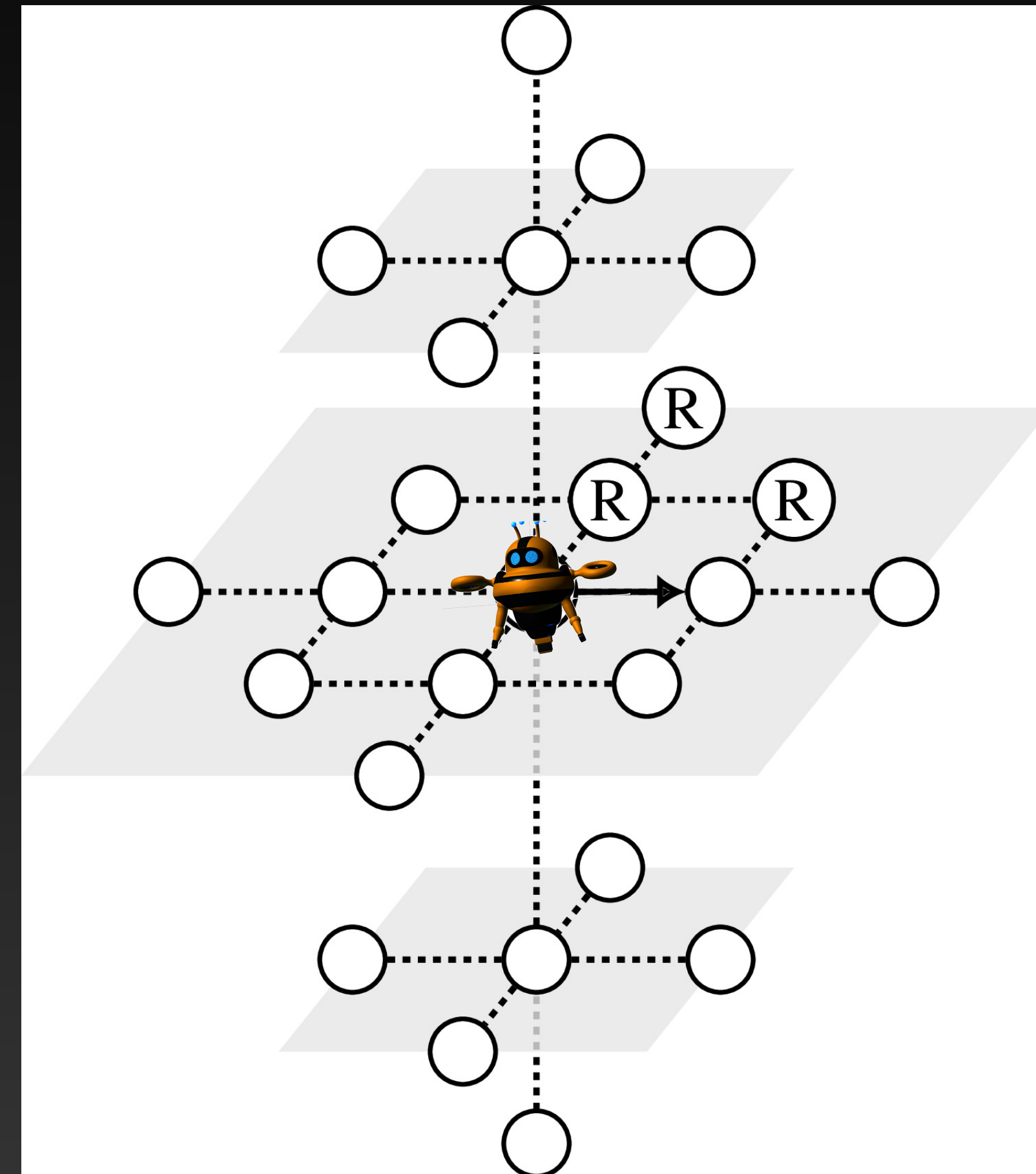
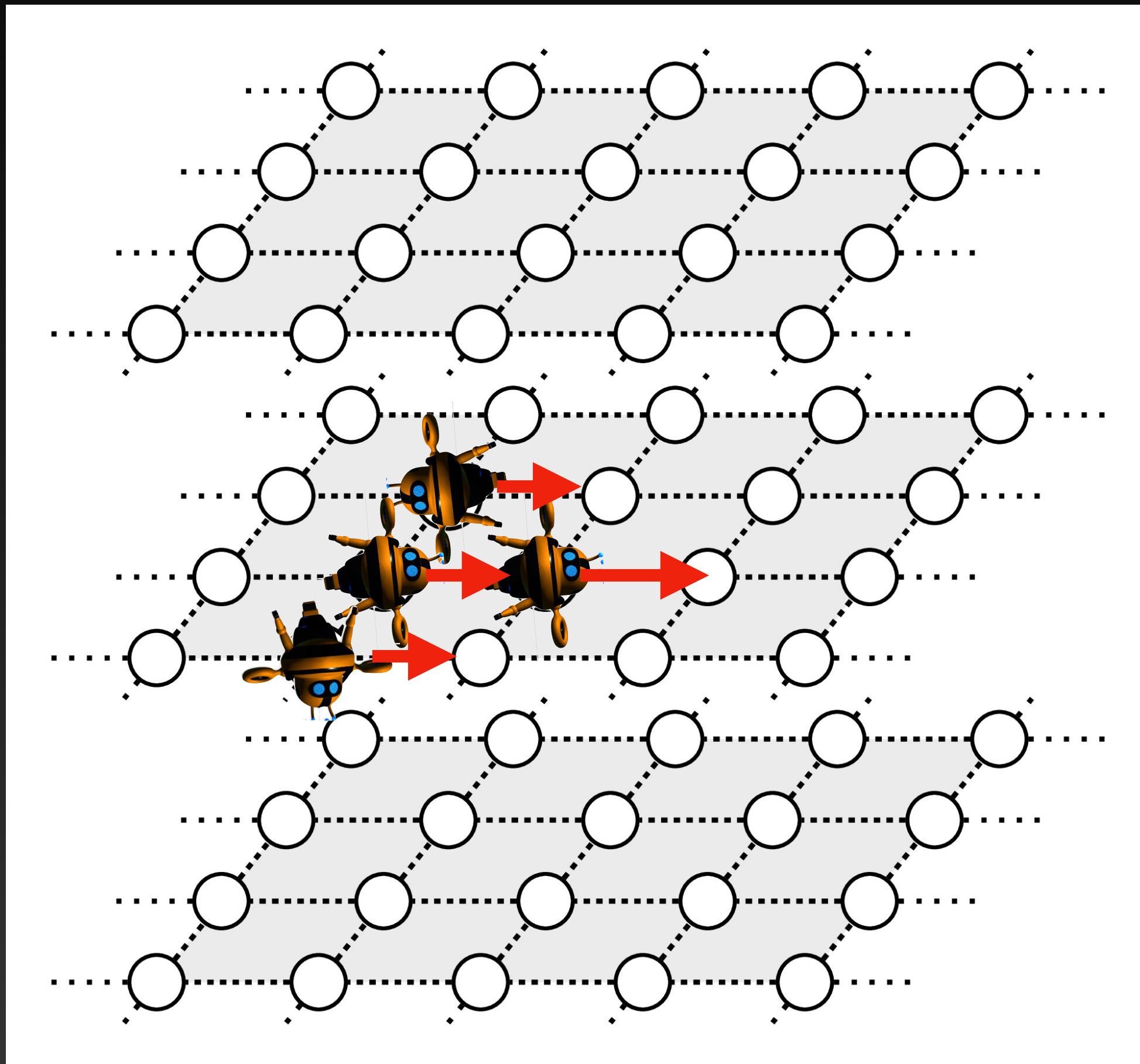


How to move straight



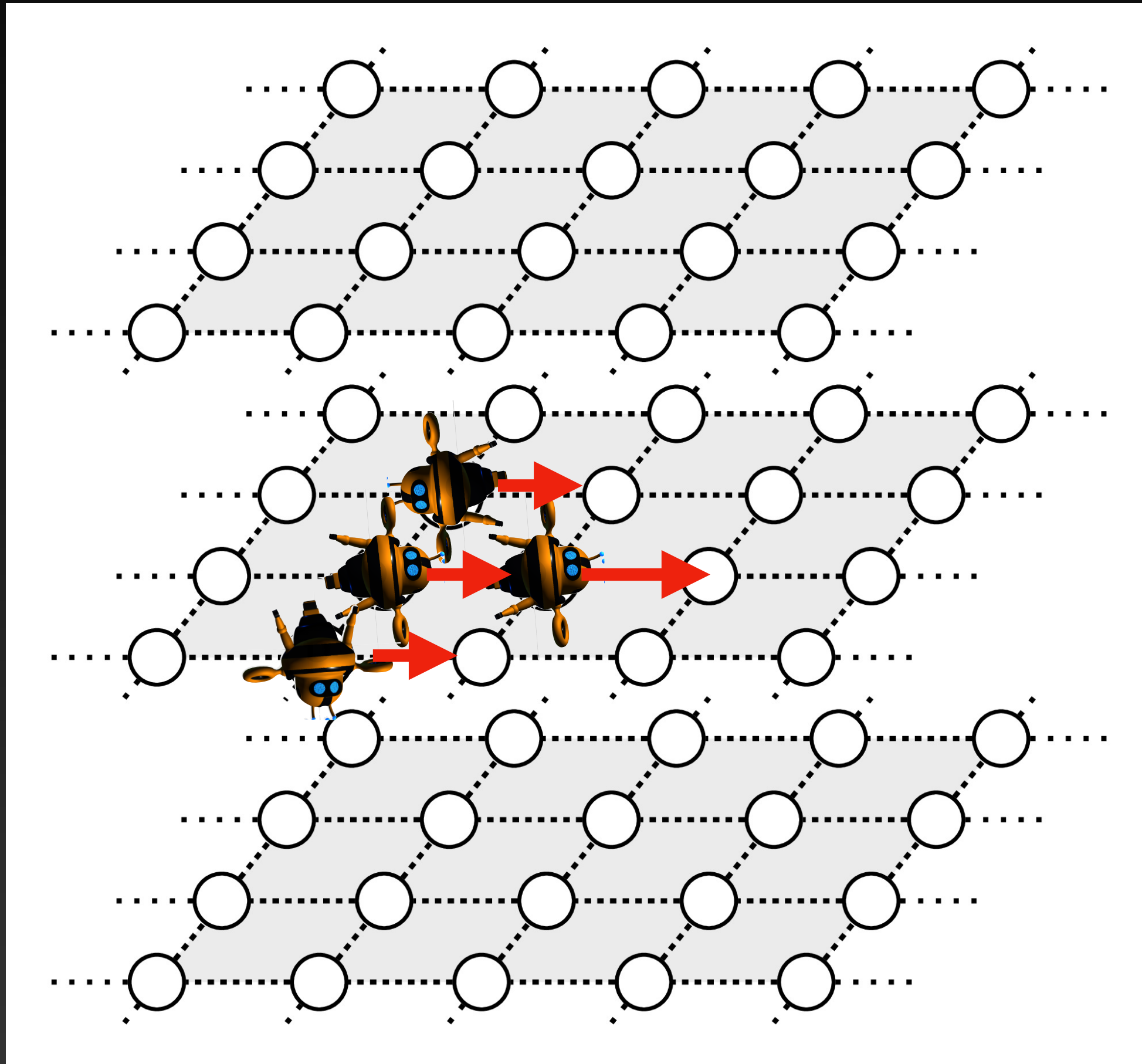
How to move straight

Look and Compute



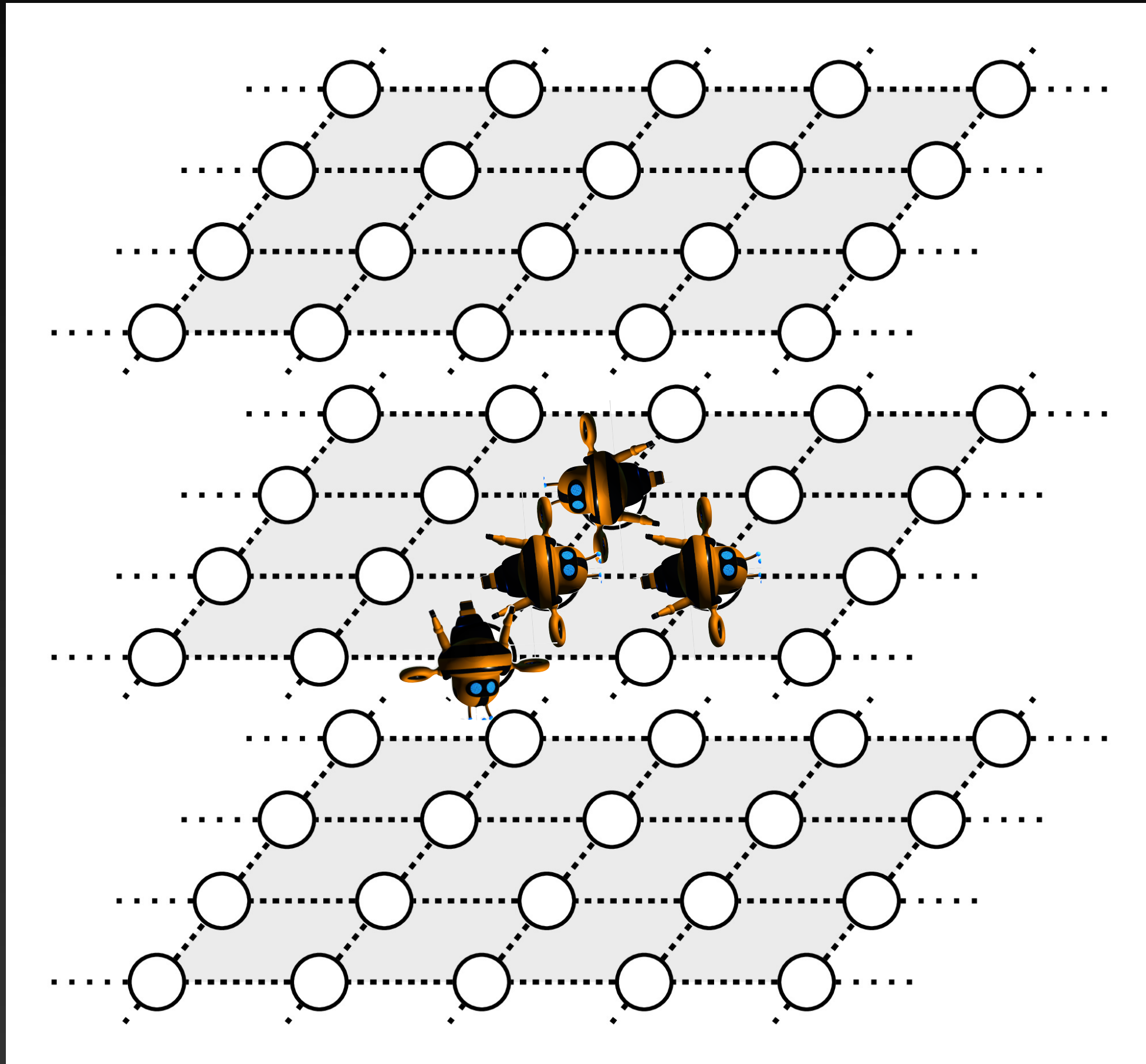
How to move straight

Move



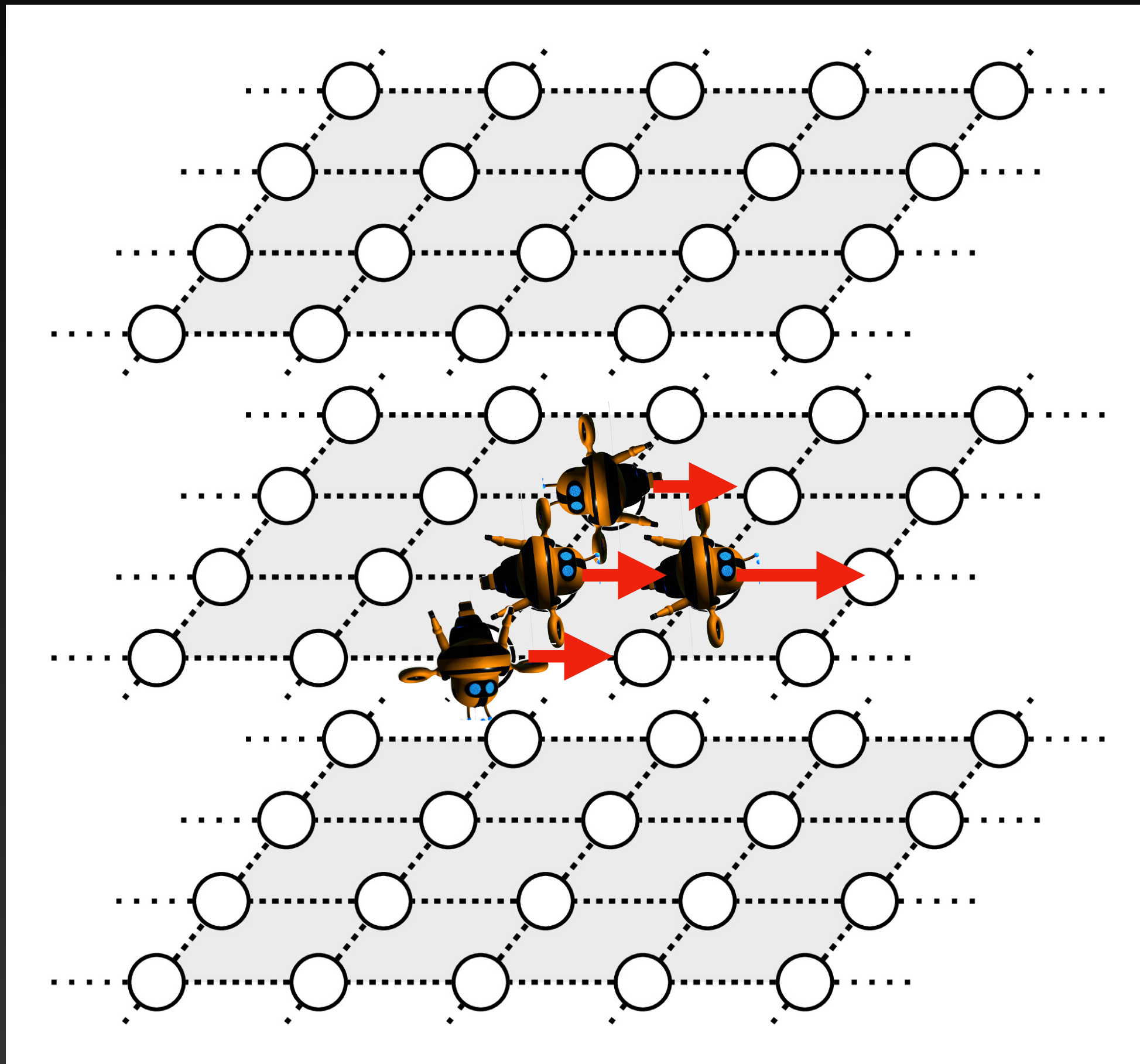
How to move straight

Move



How to move straight

Look and Compute



How to turn ?

<https://bramas.pages.unistra.fr/robot-grid-exploration-simulator/?algo1.web-algo>

<https://bramas.pages.unistra.fr/robot-grid-exploration-simulator/?algo2.web-algo>

[https://bramas.pages.unistra.fr/robot-grid-exploration-simulator/?/robot-grid-exploration-simulator/algo/finite-grid/chirality/range-2/
algo-5-robots-oblivious.web-algo](https://bramas.pages.unistra.fr/robot-grid-exploration-simulator/?/robot-grid-exploration-simulator/algo/finite-grid/chirality/range-2/algo-5-robots-oblivious.web-algo)

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robots-5-colors.web-algo](https://bramas.pages.unistra.fr/robot-grid-exploration-simulator/?/robot-grid-exploration-simulator/algo/finite-grid/chirality/range-1/3-robots-5-colors.web-algo)

Is it possible with 2 beedroids with visibility one ?

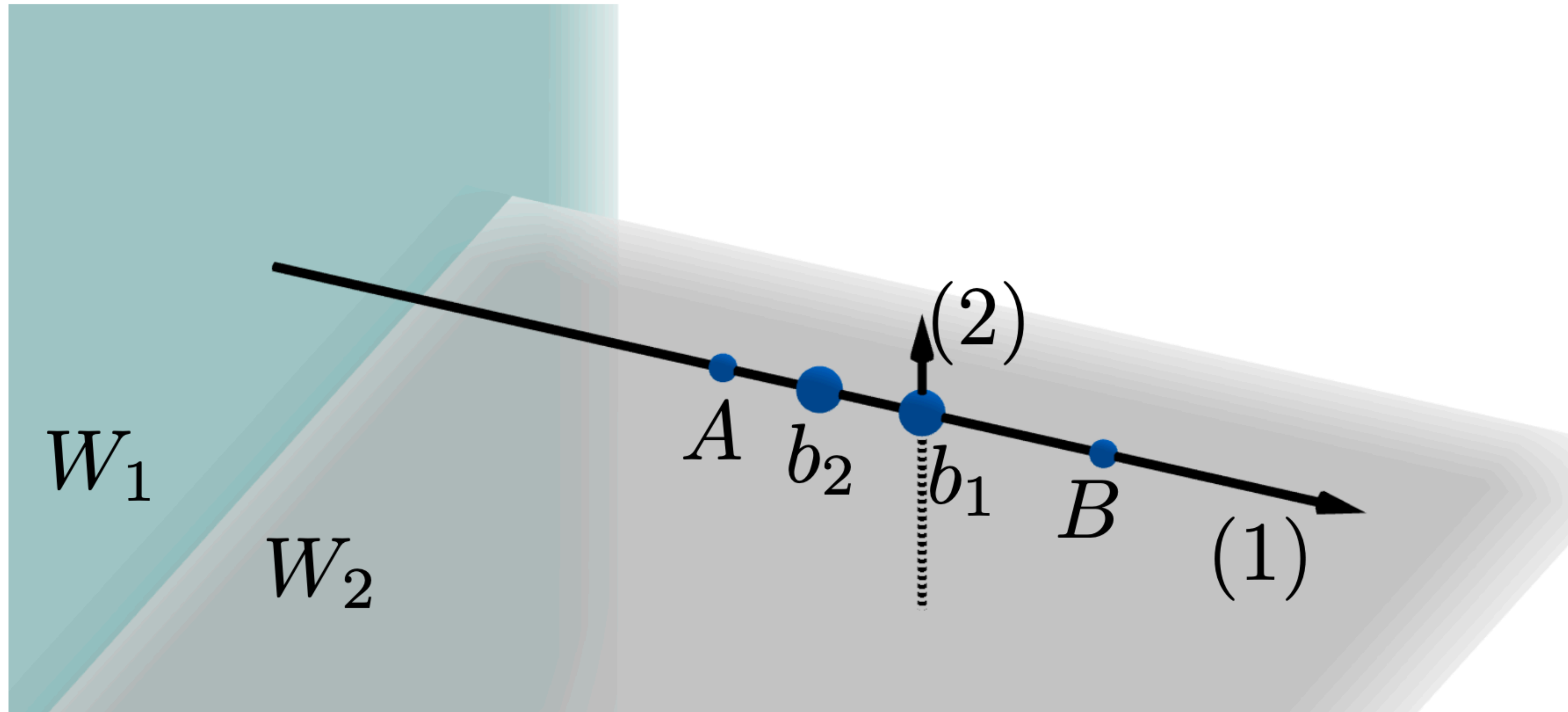
No

Proof: Hilarious

My favorite part of the proof: basically, if the two beedroids try to move away from the walls, then there exists an execution where they come back quickly close to a wall

Is it possible with 2 beedroids with visibility one ?

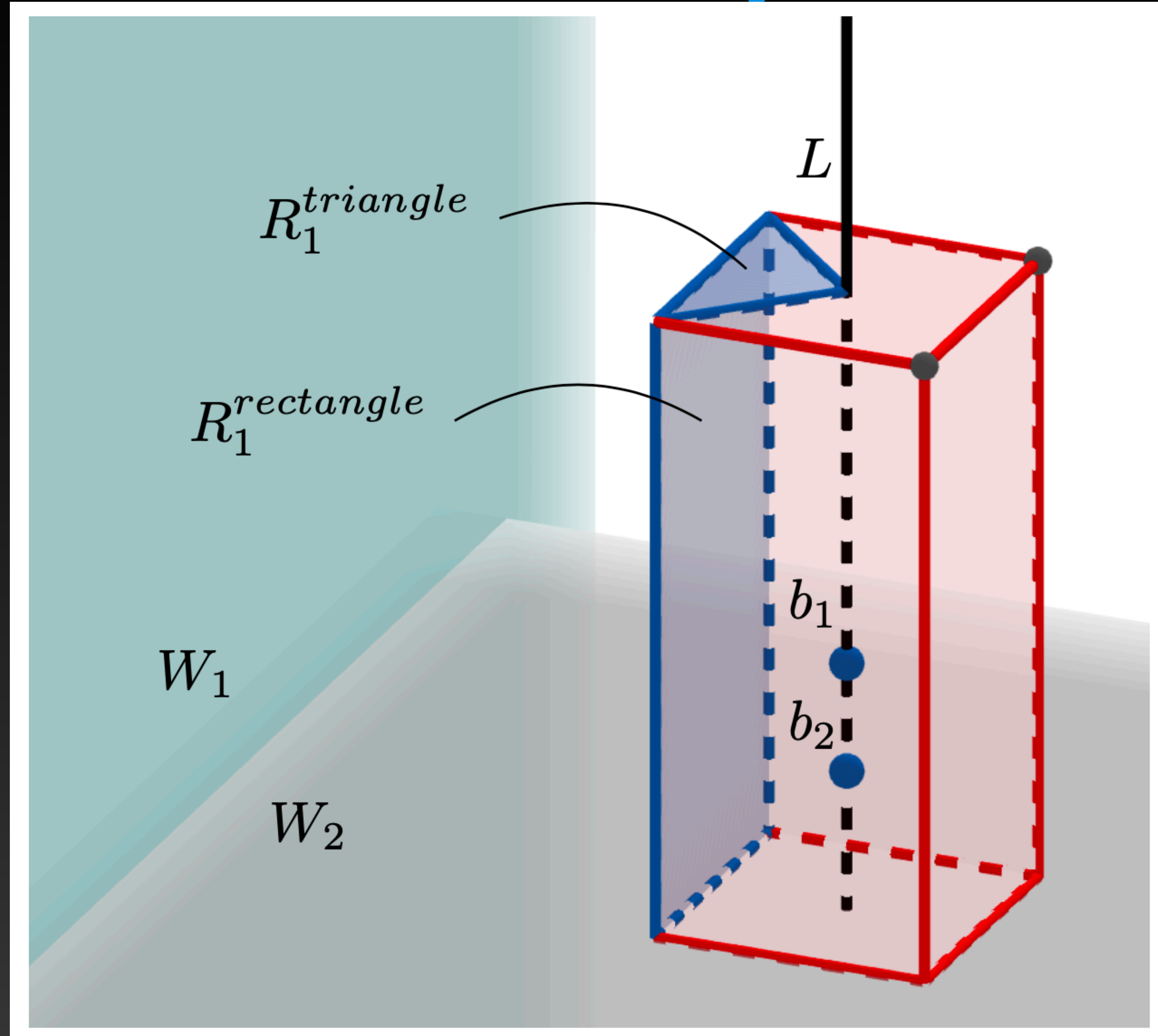
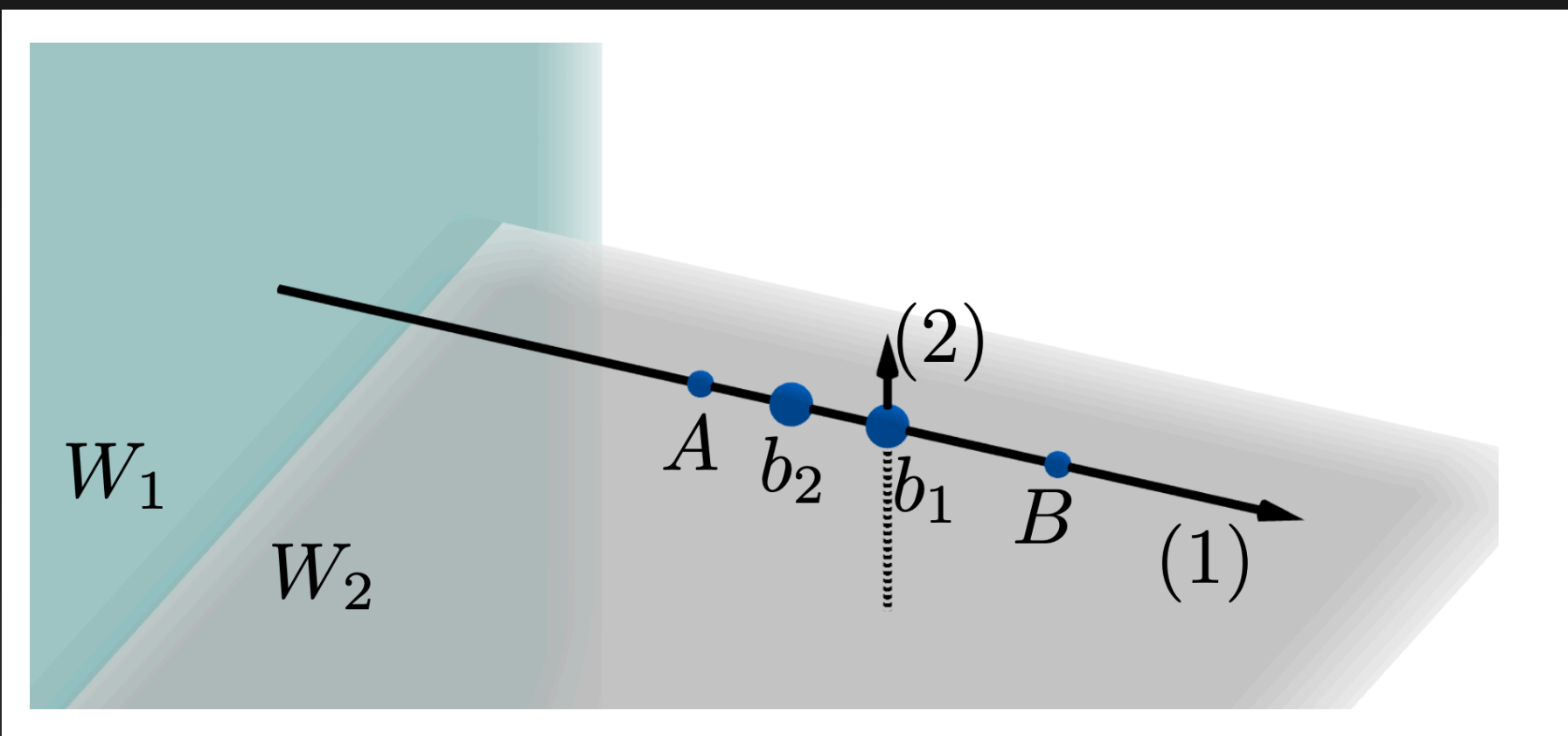
No **Proof:** Hilarious



Is it possible with 2 beedroids with visibility one ?

No

Proof: Hilarious



Summary of our contributions

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- 2 beedroids with visibility 1 cannot explore the 3D grid, even when equipped with lights
- 3 beedroids with visibility 1 and with lights, are sufficient
- 5 beedroids with visibility 2 and without lights are sufficient

Thank you